

TOSHIBA

Transistor Inverter



3-phase 200V class 0.4kW to 90kW
3-phase 400V class 0.75kW to 630kW

Variable torque Inverter TOSVERT™

VF-PS1



SAVE POWER AND SAVE MONEY

The VF-PS1 has arrived! Specially engineered to meet the global demand for energy saving and harmonic regulation.

"VF-PS1" is all you need for Industrial fan and pump application.



Photo is PS1 with LCD remote keypad option.



point 1 More energy saving

- Advanced energy-saving mode
Best for exhaust fan, primary pump, boiler and feed water pump that require energy saving.

point 2 High-frequency noise reduction and harmonics reduction

- The integrated noise filter*1 and reactor*1
Best for HVAC fan and pump.
*1 Depends on the voltage and capacity range

point 3 Built-in special softwares for fan and pump application

- Bumpless function, Fire control, Sleep function, Multi-PID control, etc
Best for exhaust fan, primary pump and HVAC fan.

point 4 Simple Setup by EASY Key

- EASY key, and 8 basic parameters
Best for exhaust fan, dust collector, drier machine and water pump.

point 5 For more flexibility and usefulness

- Built-in RS485, My function, LONWORKS® and BAC net® fieldbus options
Best for process pump and fan.

"Power Removal" safety function

Built-in Power Removal safety function which complies with EN954-1 category 3 and IEC/EN61508-1 SIL2.
It saves the installation of a line side or motor side contactor.



Totally enclosed box type for IP54



Variable torque Inverter TOSVERT™

VF-PS1

3-phase 200V class 0.4kW to 90kW
3-phase 400V class 0.75kW to 630kW

TOSVERT™ is a registered trademark of TOSHIBA CORPORATION

- Built-in thermal protection function which complies with NEC® 2005
- Comply with SEMI F47(Semiconductor Equipment and Materials International)



Voltage class	Applicable Motor Output (kW)																			
	0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	110	132	160
3-phase 200V class (P20/P00)																				
3-phase 400V class (P20/P00)																				
3-phase 400V class (P54)																				

Up to 5.5kW, 3-phase 200V class can be applied to 1-phase input power supply by using 1 size-up rating.



Contents

More energy saving	P3	Standard connections	P17
High-frequency noise reduction and harmonics reduction	P4	Terminal function	P18
Built-in special softwares for fan and pump application	P5	For inverter users	P19
Simple Setup by EASY Key	P6	Peripheral devices	P22
For more flexibility and usefulness	P7	Built-in options	P23
Function Description	P9	External options	P24
Standard specifications	P10	Totally enclosed box type for	
External dimensions	P13	IP54/UL type 12	P37

point 1 More energy saving



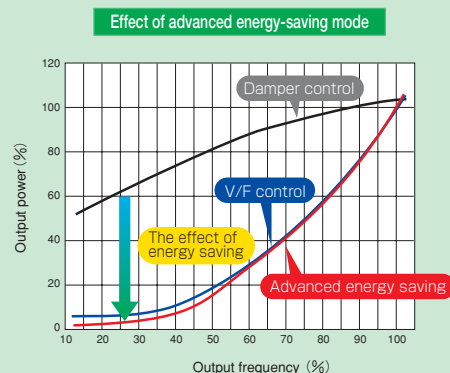
In order to meet the Kyoto protocol requirements, energy efficiency is becoming one of the top priority matters for the international organization and government.

VF-PS1 can help to achieve energy saving by the advanced energy saving mode operation.

*1:Photos of machinery are illustrative purposes only.

More energy saving

The efficiency of induction motor normally fall at the light load and low speed. The advanced energy-saving mode minimize the loss of induction motor by controlling excitation current belong to the load. Therefore, this mode increase fan and pump efficiency even in the low speed.



The Energy saved power consumption can be monitored by operation panel or through serial communication data.

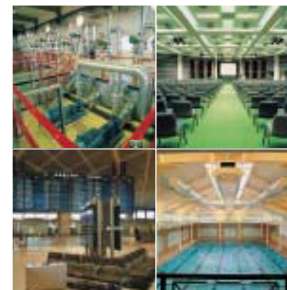


Monitor

Output power	▲	H 7.5	The inverter output power (kW) is displayed.
Integral output power	▲	H 90	The integrated amount of power (KWh) supplied from the inverter is displayed.

7.5kW motor
Output power:7.5kW
Integral output power:900kWh

point 2 High-frequency noise reduction and harmonics reduction



The integrated noise filter*2 and reactor*2 drastically reduce high-frequency noise and harmonics. The power factor and energy saving are also improved.

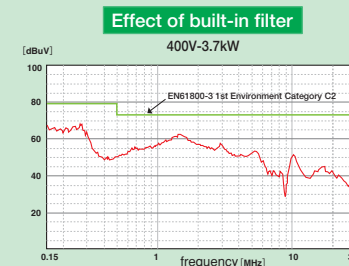
*1:Photos of machinery are illustrative purposes only.

*2:Depends on the voltage and capacity.

High-frequency Noise Reduction

Built-in noise filters are ideal for site such as commercial facilities and offices where attention must be paid to peripheral devices. Compared to filter not integrated models, space and wiring can be saved by incorporating filter in the panel. Models with built-in EMC noise filter comply with the European EMC Directive as individual inverter units.

European EMC Directive : IEC/EN61800-3, 1st Environment, C2 (200V-0.4~2.2kW)
or
IEC/EN61800-3, 2nd Environment, C3 (400V-0.75~3.7kW)



200V class models, 0.4 to 7.5kW : EMI noise filter (complies with the European EMC Directive) built-in standard
200V class models, 11 to 45kW : Basic noise filter (not complies with the European EMC Directive) built-in standard
400V class models, 0.75 to 75kW : EMI noise filter (complies with the European EMC Directive) built-in standard
400V class models, 90 to 630kW : EMI noise filter (complies with the European EMC Directive) built-in standard

Built-in EMC filter



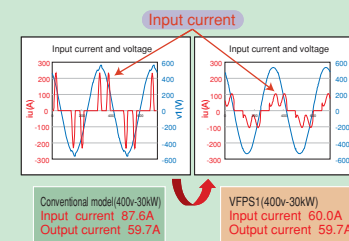
Harmonics Reduction, Power Factor Improvement

New types of compact and space-saving DC reactor is built-in for 200 V class 11 to 45 kW and 400 V 18.5 to 75 kW models.

In addition to reducing harmonics, this reactor limits the input current to 110% of the rated output current, and it has been designed to be compatible with power supply systems containing transformers, molded-case circuit breakers, and power lines.

Optional DC reactor meets IEC harmonics standards.

Effect of built-in reactor



point 3

Built-in special softwares for fan and pump application



The following functions are available for fan and pump application.

- Bumpless function and Local/Remote mode
- Fire control
- Multi-PID control
- Sleep function
- Low torque detection

*1:Photos of machinery are illustrative purposes only.

Built-in software for fan and pump application

Local/Remote mode

You can simply switch between Local and Remote by EASY key.
By switching from Remote to Local (Bumpless function), the operating frequency and status are shifted to Local mode.
It is easier for operation and adjustment.

Fire control

Fire control keeps operation with specified speed even if light fault occurs.

Multi-PID function

The PID operation can be changed at direct and inverse proportion by pressure, flow and temperature.

Sleep function (automatic stop function)

Additional energy saving can be realized by stopping at lower limit setting

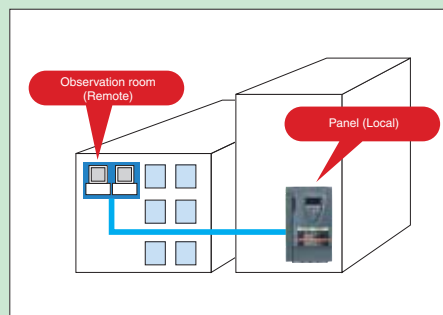
Low torque detection function

Low torque detection can notice a broken belt of AHU or low load to avoid pump trouble.

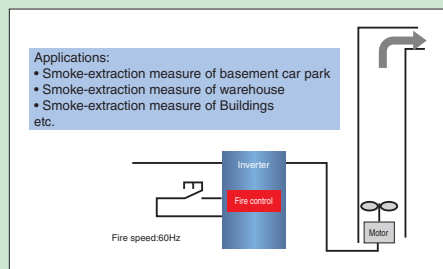
PTC thermistor input

This function is used to protect motor from overheating using the signal of PTC built-in motor.

For example:Local/Remote mode



For example:Fire control enables forced operation



point 4

Simple set up by EASY key



Installation, maintenance, and parameter setting are easier by EASY key.

You can choose, customize and display maximum of 32 parameters.

*1:Photos of machinery are illustrative purposes only.

Simple setup by EASY key

- In the Quick mode, pressing the EASY key on the panel allows you to operate the inverter by eight basic parameters. When setting each functions, press the EASY key to switch to the standard mode by one-touch operation. In this mode, you can access all parameters.

- You can customize the Quick mode display, maximum of 32target parameters are displayed to suit your specific setup requirements.

- You can also use the EASY key as a Local/Remote key to switch between Local and Remote operation, and as a shortcut key to directly access any specific setup or display screen.

EASY key



Quick mode (EASY)

Title	Function
RU4	Parameter setting macro function
Pt	V/F control mode selection
FH	Maximum frequency
ACC	Acceleration time 1
DEC	Deceleration time 1
HLr	Motor overload protection level 1
FM	FM terminal meter selection
PSEL	Parameter display selection

Easy Installation, Easy Commissioning, Easy Maintenance

Side-by-side installation

- Side-by-side installation is possible for all VF-PS1 models. You can save and optimize space inside of control panel. Heat sink can be installed outside of the panel as an option.

Removable control terminal board

- A removable terminal board allows you to use the control wiring when replacing the inverter, which also makes maintenance easier.

ON/OFF control of cooling fan

- Temperature-based cooling fan ON/OFF control reduces sound noise, saves energy, and extends the cooling fan's life.

Monitoring of serviceable service parts/alarm output

- The expected replacement cycle of main circuit capacitors, capacitors on control board, and cooling fan is monitored. And alarm is raise when the cycle is reached to the expected replacement time

Side-by-side installation



Removable control terminal board



Communications and Network

RS-485 communications

RS-485 communications is equipped as standard. Modbus-RTU protocol and TOSHIBA protocol is also supported.

Network options

DeviceNet[®]*, PROFIBUS, CC-Link[®]*, LONWORKS[®]*, BACnet[®]*, Metasys[®]N2*¹ and APOGEE[®]FLN*¹ are also available.

Data tracing

The PCMO01Z communication software allows you to edit, monitor, and trace parameter data on a PC, enabling easier data management from inverter



*1 DeviceNet is a registered trademarks of ODVA (Open DeviceNet Vendor Association). CC-Link is a registered trademarks of Mitsubishi Electric Corporation. LONWORKS is a registered trademark of Echelon Corporation. BACnet is a registered trademark of American Society of Heating, Refrigerating and Air-Conditioning Engineers, Incorporated. Metasys N2 is a registered trademark of Johnson Controls, Incorporated. APOGEE FLN is a registered trademark of Siemens Building Technologies, Incorporated.

Customizing by "My Function"

Using "My function", you can create programs up to 28 steps. This achieves logic operations and internal data operations. Parameters can also be set by analog input and minimum-peak hold of analog outputs.

For example:

- (Ex.1) Inverter is automatically switched to commercial operation without external sequence when the inverter is tripped.
 (Ex.2) A signal is output when torque reaches 120% and frequency is 5 Hz.
 (Ex.3) "Forward rotation operation," "preset-speed operation frequency 3" and "No.2 acceleration/deceleration" are simultaneously turned ON by input on a single terminal.
 (Ex.4) The acceleration/deceleration time is changed dynamically by a voltage within the range 0 to 10 V.

My function

Number of program steps : 28
 Internal relays : 8
 Internal counters : 2
 Logic commands : ST, STN, AND, ANDN, OR, ORN, SET, RSET, HOLD, ON/OFF DELAY TIMER
 Data commands : EQ, NE, GT, GE, LT, LE, ASUB

Safety Environmental Compatibility

Ambient temperature 60°C

The VF-PS1 can be used at a rating up to an ambient temperature of 50°C or 45°C and in environments up to 60°C at a reduced current.

Eco Design

88% materials used on the VF-PS1 are recyclable, which was designed more than meets of the European WEEE (Waste Electrical and Electronic Equipment) Directive of 70%.

Power section IP54 all sizes

Complete isolation frame outer atmosphere. Option kit can be used to mount the power part of the drive outside the enclosure. (IP 54 degree of protection)

12-pulse input connections

The 500~630kW class can suppress the harmonic current substantially by 12-pulses input connections.
 *12-pulse input requires a special transformer

Useful Options

LCD Remote Keypad Option



This panel indicates 8-line of 23 letters and can be used for simple setup and monitoring by selection of parameters using the jog dial.

Type: RKP004Z

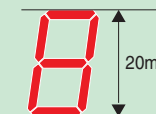


LED Remote Keypad Option



20 mm LEDs, ensure outstanding visibility even in the darkness. It is designed to be mounted on the panels as extension display or remote keypad. In addition, parameter copy and storing function is also available

Type: RKP002Z



Expanded Terminal Block Option Fieldbus Option



I/O terminal block can be added for more complicated operation and wide range of systems:

- Contact inputs (4) • Contact outputs (2) • Analog inputs (2)
- Analog outputs (2) • PTC input (1) • Relay output (1 circuit)
- Pulse train input (1)

For more information, refer to page 23.

Type: ETB003Z, ETB004Z



Main fieldbuses as built-in option card are supported for space saving and centralized control systems.

- DeviceNet[®] Type: DEV002Z
- PROFIBUS Type: PDP002Z
- CC-Link Type: CCL001Z
- LONWORKS[®] Type: LIU006Z
- BAC net[®] Type: BCN001Z
- Metasys[®]N2 Type: MTS001Z
- APOGEE[®]FLN Type: APG001Z

Basic functions

Each “setup item” that determines the control characteristics of the inverter is called a “parameter.”
For example, to change the acceleration time, you choose the acceleration time parameter (titled “ $R\zeta\zeta$ ”).

Quick mode (EASY)

To enter the Quick mode, press the EASY key on the panel. In this mode, you can set eight of the basic parameters.

Standard mode

In this mode, you can set all parameters.
For details of parameters, refer to the Instruction Manual.



Title	Function
$R\zeta\zeta$	Parameter setting macro function
$P\zeta$	V/f control mode selection
$F\zeta$	Maximum frequency
$R\zeta\zeta$	Acceleration time 1
$d\zeta\zeta$	Deceleration time 1
$\zeta H r$	Motor overload protection level 1
$F\zeta$	FM terminal meter adjustment
$P\zeta\zeta L$	Parameter display selection

Basic parameters

Title	Function	Adjustment Range	Default
$F\zeta$	Frequency of operation panel	$L\zeta - U\zeta$ Hz	0
$R\zeta\zeta$	History function		-
$R\zeta\zeta$	Automatic acceleration/deceleration	0:Disabled 1:Automatic setting 2:Automatic setting (during acceleration only)	0
$R\zeta\zeta$	Automatic torque boost	0:Disabled 1:Automatic torque boost + auto-tuning 1 2: Sensorless vector control 1+ auto-tuning 1	0
$R\zeta\zeta$	Automatic function setting	0:Disabled 1:Frequency setting by means of voltage 2:Frequency setting by means of current 3:Voltage/current switching from external terminal 4:Frequency setting on operation panel and operation by means of terminals 5: Frequency setting and operation on operation panel	0
$\zeta\zeta\zeta$	Command mode selection	0:Terminal input enabled 1:Operation panel input enabled (including LED/LCD option input) 2:Operation panel RS485 (2-wire) communication input 3:Internal RS485 (4-wire) communication input 4:Communication option input	0
$F\zeta\zeta\zeta$	Frequency setting mode selection 1	1:V/f (voltage/current input) 2:RR/S4 (potentiometer/voltage input) 3:RX (voltage input) 4:Operation panel input enabled (including LED/LCD option input) 5:Operation panel RS485 (4-wire) communication input 6:Internal RS485 (4-wire) communication input 7:Communication option input 8:Optional AI1 (differential current input) 9:Optional AI2 (voltage/current input) 10:UP/DOWN frequency 11:RP pulse input 12:High-speed pulse input 13:Binary/BCD input	2
$P\zeta$	V/f control mode selection	0:Constant torque characteristics 1:Voltage decrease curve 2:Automatic torque boost 3:Sensorless vector control (speed) 4:- 5:V/f 5-point setting 6:PM control 7:PG feedback vector control (speed) 8:- 9:Energy-saving 10:Advanced energy-saving	0
$u\zeta$	Manual torque boost 1	0.0-30.0%	Depends on the capacity
$u\zeta$	Base frequency 1	25.0-500.0Hz	WN-60, WP-50.0
$u\zeta u$	Base frequency voltage 1	200V class:50-330V 400V class:50-660V	Depends on the capacity
$F\zeta$	Maximum frequency	30.0-500.0Hz	80.0
$U\zeta$	Upper limit frequency	0.0-F Hz	WN-60.0, WP-50.0
$L\zeta$	Lower limit frequency	0.0-U Hz	Depends on the capacity
$R\zeta\zeta$	Acceleration time 1	0.1-6000 sec.	Depends on the capacity
$d\zeta\zeta$	Deceleration time 1	0.1-6000 sec.	Depends on the capacity
$R\zeta F\zeta$	RR/S4 input point 2 frequency	0.0-F Hz	WN-60.0, WP-50.0
$R\zeta F\zeta$	V/f input point 2 frequency	0.0-F Hz	WN-60.0, WP-50.0
$S\zeta r\zeta$	Preset speed operation frequency 1	$L\zeta - U\zeta$ Hz	0.0
$S\zeta r\zeta$	Preset speed operation frequency 2	$L\zeta - U\zeta$ Hz	0.0
$S\zeta r\zeta$	Preset speed operation frequency 3	$L\zeta - U\zeta$ Hz	0.0
$S\zeta r\zeta$	Preset speed operation frequency 4	$L\zeta - U\zeta$ Hz	0.0
$S\zeta r\zeta$	Preset speed operation frequency 5	$L\zeta - U\zeta$ Hz	0.0
$S\zeta r\zeta$	Preset speed operation frequency 6	$L\zeta - U\zeta$ Hz	0.0
$S\zeta r\zeta$	Preset speed operation frequency 7	$L\zeta - U\zeta$ Hz	0.0
$F\zeta$	Forward run/reverse run selection (operation panel operation)	0:Forward run 1:Forward run 2:Forward run (Forward/reverse switchable on operation panel) 3:Reverse run (Forward/reverse switchable on operation panel)	0
$\zeta H r$	Motor overload protection level 1	10-100%	100
$\zeta\zeta\zeta$	Motor overload protection characteristic selection	Setting Motor type Overload protection OL stall	0
		0 (protect) Standard Motor X (not stall)	
		1 (protect) X (not stall)	
		2 (not protect) X (not stall)	
		3 (not protect) X (not stall)	
		4 (protect) X (not stall)	
		5 (protect) X (not stall)	
		6 (not protect) X (not stall)	
		7 (not protect) X (not stall)	
$d\zeta P\zeta$	Current/voltage unit selection	0%, 1A (ampere)/V (volt)	0
$F\zeta\zeta\zeta L$	FM terminal meter selection	0-64 (0:Output frequency, 1:Frequency command value, 2:Output current, 3:Input voltage, 4:Output voltage, etc.)	0
$F\zeta\zeta$	FM terminal meter adjustment	-	-
$R\zeta\zeta\zeta L$	AM terminal meter selection	0-64 (0:Output frequency, 1:Frequency command value, 2:Output current, 3:Input voltage, 4:Output voltage, etc.)	2
$R\zeta\zeta$	AM terminal meter adjustment	-	-
ζF	PMW carrier frequency	1.0-16.0kHz (large capacity model 2.5-8.0kHz)	Depends on the capacity
$U\zeta\zeta$	Auto-restart control selection	0:Deselect 1:At auto-restart 2:ST ON/OFF switching 3:1+2 4:Starting	0
$U\zeta\zeta$	Regenerative power ride-through control	0:Deselect 1:Power ride-through 2:Deceleration stop during power failure 3:Synchronized deceleration/acceleration (synchronized acceleration/deceleration signal) 4:Synchronized deceleration/acceleration (synchronized acceleration/deceleration signal+power failure)	0
$P\zeta\zeta$	Dynamic braking selection	0:Deselect 1:Select (braking resistance overload detect) 2:Select (braking resistance overload not detect)	0
$P\zeta\zeta r$	Dynamic braking resistance	0.5-1000Ω	Depends on the capacity
$P\zeta\zeta P$	Allowable continuous braking resistance	0.01-600.0kW	Depends on the capacity
$\zeta y P$	Factory default setting	0:- 1:50 Hz default setting 2:60 Hz default setting 3:Factory default setting 4:Trip cleared 5:Cumulative operation time cleared 6:Type information initialized 7>User-defined parameter recorded 8:Item 7 above reset 9:Cumulative fan operation time cleared 10:Acceleration/deceleration time setting 0.01 sec.-600.0 sec. 11:Acceleration/deceleration time setting 0.1 sec.-6000sec.	0
$P\zeta\zeta\zeta L$	Parameter display selection	0:Standard setting mode at time of activation of motor 1:Quick mode at time of activation of motor 2:Quick mode only	0
$F\zeta\zeta\zeta - F\zeta\zeta\zeta$	Extended parameters	Set parameters in more detail.	-
$\zeta\zeta\zeta\zeta$	Automatic edit function	-	-

Extended parameters

About 400 extended parameters are available. For details on extended parameters, please visit our web site (<http://www.inverter.co.jp/>).

Standard specifications

Standard specifications (200 V class - 0.4 to 45 kW, 400 V class -0.75 to 75 kW model)

200 V class

Item		Specification													
Applicable Motor (kW)		0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45
Rating	Type	VFPS1–													
	Form	2004PL	2007PL	2015PL	2022PL	2037PL	2055PL	2075PL	2110PM	2150PM	2185PM	2220PM	2300PM	2370PM	2450PM
	Output Capacity (kVA) <small>Note 1)</small>	1.1	1.8	3.0	4.2	6.7	10	13	21	25	29	34	46	55	67
	Output Current (A) <small>Note 2)</small>	3.0 (3.0)	4.8 (4.5)	8.0 (8.0)	11 (10.5)	17.5 (16.6)	27.5 (25.0)	33 (33)	54 (49)	66 (64)	75 (66)	88 (75)	120 (88)	144 (120)	176 (140)
	Output Voltage	3-phase, 200 to 240 V (The maximum output voltage is the same as the input voltage.)													
	Overload Current Rating	120%–1 minute 135%–2 seconds													
Electric Braking	Dynamic	Built-in													
	Braking Circuit	Built-in													
	Dynamic Braking Resistor	External options													
Power Supply	Voltage/frequency	3-phase, 200 to 240 V – 50/60 Hz													
	Allowable Fluctuation	Voltage +10% - 15% <small>Note 3)</small> Frequency ±5%													
Cooling	Protective method	IP20 enclosed type (JEM1030)									IP00 enclosed type (JEM1030) <small>Note 4)</small>				
	Cooling method	Forced air cooling													
	Cooling fan noise (dBA)	43	43	43	55	55	56	58	60	60	60	60	64	64	64
	Color	RAL7016													
DC Reactor	Built-in Filter	EMI noise filter <small>Note 5)</small>						Basic noise filter <small>Note 6)</small>							
	DC Reactor	External option						Built-in							

400 V class

Item		Specification														
Applicable Motor (kW)		0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75
Rating	Type	VFPS1-														
	Form	4007PL	4015PL	4022PL	4037PL	4055PL	4075PL	4110PL	4150PL	4185PL	4220PL	4300PL	4370PL	4450PL	4550PL	4750PL
	Output Capacity (kVA) <small>Note 1)</small>	1.8	3.1	4.4	8.0	11	13	21	25	31	37	50	60	72	88	122
	Output Current (A) <small>Note 2)</small>	2.3 (2.3)	4.1 (4.0)	5.8 (5.3)	10.5 (8.6)	14.3 (13)	17.6 (17)	27.7 (25)	33 (32)	41 (37)	48 (38)	66 (53)	79 (60)	94 (75)	116 (93)	160 (120)
	Output Voltage	3-phase, 380 to 480 V (The maximum output voltage is the same as the input voltage.)														
	Overload Current Rating	120%–1 minute 135%–2 seconds														
Electric Braking	Dynamic	Built-in														
	Braking Circuit	Built-in														
	Dynamic Braking Resistor	External options														
Power Supply	Voltage/frequency	3-phase, 380 to 480 V – 50/60 Hz														
	Allowable Fluctuation	Voltage +10% - 15% <small>Note 3)</small> Frequency ±5%														
	Protective method	IP20 enclosed type (JEM1030)									IP00 enclosed type (JEM1030) <small>Note 4)</small>					
	Cooling method	Forced air cooling														
	Cooling fan noise (dBA)	43	43	43	55	56	56	58	60	60	60	64	64	64	64	64
	Color	RAL7016														
	Built-in Filter	EMI noise filter <small>Note 5)</small>														
	DC Reactor	External option									Built-in					

Note 1) Capacity is calculated at 220V for the 200V models and at 440V for the 400V models.

Note 2) Rated output current when the PWM carrier frequency (parameter ζF) is 4kHz or less.

The values in parentheses refer to rated output currents when set to 12kHz.

Note 3) ±10% when the inverter is used continuously (load of 100%)

Note 4) Inverters, 18.5kW or greater, do not have wiring port covers. They have large openings, but there is no space to bend the external cables inside the unit. If they are fitted external to the cabinet, please use an optional wiring port cover.

Note 5) Complies with the European EMC Directive IEC/EN61800-3, 1st environment, category C2 or IEC/EN61800-3, 2nd environment, category C3

Note 6) Not complies with the European EMC Directive Core and capacities with external filter (optional) : Complies with the European EMC Directive.

Standard specifications

■ Standard specifications (200 V class -55 to 75 kW, 400 V class -90 to 630 kW model)

200 V class

Item		Specification		
Applicable Motor (kW)		55	75	90
Rating	Type	VFPS1-		
	Form	2550P	2750P	2900P
	Output Capacity (kVA) Note 1)	84	109	137
	Output Current (A) Note 2)	221	285	359
	Output Voltage	3-phase, 200 to 240 V (The maximum output voltage is the same as the input voltage.)		
Overload Current Rating		120%~1 minute 135%~2 seconds		
Electric Braking	Dynamic Braking Circuit	Built-in		
	Dynamic Braking Resistor	External options		
Power Supply	Voltage/frequency	3-phase, 200 to 240 V ~ 50/60 Hz		
	Allowable Fluctuation	Voltage +10% – 15% Note 3) Frequency ±5%		
Protective method		IP20 enclosed type (JEM1030) Note 4)		
Cooling method		Forced air cooling		
Cooling fan noise (dBA)		61	61	70
Color		RAL7016		
Built-in Filter		External filter (optional)		
DC Reactor		Attached DC reactor Note 5)		

400 V class

Item		Specification										
Applicable Motor (kW)		90	110	132	160	220	250	280	315	400	500	630
Rating	Type	VFPS1-										
	Form	4900PC	4110KPC	4132KPC	4160KPC	4220KPC	4250KPC	4280KPC	4315KPC	4400KPC	4500KPC	4630KPC
	Output Capacity (kVA) Note 1)	136	164	197	239	325	367	419	469	578	717	905
	Output Current (A) Note 2)	179	215	259	314	427	481	550	616	759	941	1188
	Output Voltage	3-phase, 380 to 480 V (The maximum output voltage is the same as the input voltage.)										
Overload Current Rating		120%~1 minute, 135%~2 seconds										
Electric Braking	Dynamic Braking Circuit	Built-in					External options					
	Dynamic Braking Resistor	External options										
Power Supply	Voltage/frequency	Note 6)		3-phase, 380 to 440 V ~ 50 Hz 3-phase, 380 to 480 V ~ 60 Hz								
	Allowable Fluctuation	Voltage +10% ~ 15% Note 3) Frequency ±5%										
Protective method		IP20 enclosed type (JEM1030) Note 4)										
Cooling method		Forced air cooling										
Cooling fan noise (dBA)		61	61	72	73	73	76	76	76	76	76	78
Color		RAL7016										
Built-in Filter		EMI noise filter Note 7)										
DC Reactor		Attached DC reactor Note 5)										

Note 1) Capacity is calculated at 220V for the 200V models and at 440V for the 400V models.

Note 2) Indicates the value when the PWM carrier frequency (parameter ζF) is 2.5 kHz or less.

When low noise (PWM carrier frequency 8 kHz) is required at 18.5 kW or more, use an inverter of capacity one rank higher than the motor capacity.

Note 3) ±10% when the inverter is used continuously (load of 100%)

Note 4) Inverters, 18.5kW or greater, do not have wiring port covers. They have large openings, but there is no space to bend the external cables inside the unit. If they are fitted external to the cabinet, please use an optional wiring port cover.

Note 5) For 200V-55kW, 400V-90kW or larger model, be sure to install DC reactor.

However, this is unnecessary for DC input specifications.

Note 6) Three-phase 380~480V-50/60Hz

Note 7) Complies with the European EMC Directive

IEC/EN61800-3, 2nd environment, category C3

■ Common Specifications

	Item	Specification	
Control specifications	Control system	Sinusoidal PWM control	
	Output voltage adjustment	Main circuit voltage feedback control. (Switchable between automatic adjustment/fix/control off)	
	Output frequency range	Setting between 0.01 to 500Hz. Default max. frequency is set to 0.01 to 60Hz. Maximum frequency adjustment (30 to 500Hz)	
	Minimum setting steps of frequency	0.01Hz: operation panel input (60Hz base), 0.02Hz: analog input (60Hz base, 11 bit/0 to 10Vdc)	
	Frequency accuracy	Within ±0.2% (25°C±10°C); analog input ±0.01% (25°C±10°C); digital input	
	Voltage/frequency characteristics	V/f constant, square reduction torque control, automatic torque boost, vector calculation control, base frequency adjustment 1 and 2 (25 to 500Hz), V/f 5-point arbitrary setting, torque boost adjustment (0 to 30%), start frequency adjustment (0 to 10Hz), stop frequency adjustment (0 to 30Hz)	
	Frequency setting signal	3kΩ potentiometer (possible to connect to 1 to 10kΩ-rated potentiometer) 0 to 10Vdc (input impedance Zin: 30kΩ) 0 to ±10Vdc (Zin: 22kΩ) 4 to 20mAdc (Zin:242Ω)	
	Terminal board base frequency	The characteristic can be set arbitrarily by two-point setting. Compliant with 6 types of input: analog input (RR, V/II, RX, RX2), pulse input and binary/BCD input (*RX2, binary/BCD input: optional)	
	Frequency jump	3 places. Setting of jump frequency and width.	
	Upper and lower limit frequencies	Upper limit frequency: 0 to max. frequency, lower limit frequency: 0 to upper limit frequency	
PWM carrier frequency	200V-45kW or less, adjustable between 1.0 to 16kHz for 400V-75kW or less/200V-55kW or less, adjustable between 2.5 to 8kHz for 400V-90kW or more		
PID control	Adjustment of proportional gain, integral time, differential time and delay filter		
Operation specifications	Acceleration/deceleration time	0.01 to 6000 sec. Selectable from among acceleration/deceleration. times 1 and 2. Automatic acceleration/deceleration function. S-pattern acceleration/deceleration 1 and 2 pattern adjustable.	
	DC braking	Adjustment of braking start frequency (0 to 120Hz), braking (0 to 100%) and braking time (0 to 10 sec.). With emergency stop braking function and motor shaft fix control function.	
	Forward run/reverse run Note 1)	With F-CC closed to forward run, with R-CC closed to reverse run, with both closed to reverse run. With ST-CC opened to coast stop. Emergency stop by panel operation or terminal board.	
	Jog run Note 1)	Jog mode, if selected, allows jog operation from the operation panel Jog run operation by terminal board is possible by setting the parameters.	
	Preset speed operation Note 1)	By changing the combination of open/close between S1, S2, S3, RRV54-CC, set frequency + 15-speed operation. Selectable between acceleration/deceleration time, torque limit and V/f by set frequency.	
	Retry	Capable of restarting after a check of the main circuit elements in case the protective function is activated. Max. 10 times selectable arbitrarily. Waiting time adjustment (0 to 10 sec.)	
	Soft stall	Automatic load reduction control at overloading. (Default: OFF)	
	Cooling fan ON/OFF	The cooling fan will be stopped automatically to assure long life when unnecessary.	
	Operation panel key operation ON/OFF control	Key prohibition selectable between Stop key only, Mode key only, etc. All key operations can be prohibited.	
	Regenerative power ride-through control	Possible to keep the motor running using its regenerative energy in case of a momentary power failure. (Default: OFF)	
Protective function	Auto-restart operation	Possible to restart the motor in coasting in accordance with its speed and direction. (Default: OFF)	
	Commercial inverter switching	Possible to switch operation by commercial power source or inverter	
	Drooping function	When two or more inverters are used to operate a single load, this function prevents load from concentrating on one inverter due to unbalance.	
	Override function	External input signal adjustment is possible to the operation frequency command value.	
	Protective function	Stall prevention, current limit, overcurrent, overvoltage, short circuit on the load side, ground fault on the load side (Note 5), undervoltage, momentary power failure (15ms or more), non-stop control at momentary power failure, overload protection, arm overload at starting, overcurrent on the load side at starting, overcurrent and overload at dynamic braking resistance, fan overheat, emergency stop	
	Electronic thermal characteristic	Switchable between standard motor/constant torque VF motor, adjustment of overload protection and stall prevention level.	
	Reset	Reset by 1a contact closed (or 1b contact opened), or by operation panel. Or power source OFF/ON. This function is also used to save and clear trip records.	
	Display functions	Alarms	Stall prevention during operation, overload limit, overload, undervoltage on power source side, DC circuit undervoltage, setting error, in retry, upper limit, lower limit.
		Causes of failures	Overcurrent, overvoltage, fan overheat, short circuit on the load side, ground fault on the load side, inverter overload, arm overcurrent at starting, overcurrent on the load side at starting, EEPROM error, RAM error, ROM error, transmission error, (dynamic braking resistor overcurrent/overload), (emergency stop), (undervoltage), (low current), (over torque), (motor overload), (output phase failure) The items in the parentheses are selectable.
		Monitoring function	Operation frequency, operation frequency command, forward run/reverse run, output current, DC voltage, output voltage, compensated frequency, terminal board input/output information, CPU version, control EEPROM version, past trip history, cumulative operation time, speed feedback, torque, torque command, torque current, setting current, PID feedback value, motor overload factor, inverter overload factor, PBR overload factor, PVBR load factor, input power, output power, peak output current, peak DC voltage, Motor counter pseudo PG, position pulse, RR input, V/II input, RX input, RX2 input, FM output, AM output, meter adjustment fix output, flash memory version, main circuit EEPROM version, types of connection option, previous default setting, previous automatic control (AU2)
Free unit display		Display of optional units other than output frequency (motor speed, line speed, etc), current ampere/% switch, voltage volt/% switch	
Automatic edit function		Searches automatically parameters that are different from the standard default setting parameters. Easy to find changed parameters.	
LED	User default setting	User parameter settings can be saved as default settings. Allows to reset the parameters to the user-defined parameter settings.	
	Charge display	Displays main circuit capacitor charging.	
	Power Removal safety function	Built-in Power Removal safety function which complies with EN954-1 category 3 and IEC/EN61508-1 SIL2.	
Output signal	Input/output terminal input function	Possible to select positive logic or negative logic with programmable input/output terminal function menu. Note 1: Note 2: (Default setting: positive logic)	
	Sink/source switching	Possible to switch between minus common (CC) and plus common (P24) for control terminal. (Default setting: minus common (CC))	
	Failure detection signal	1c contact output (250Vac-2A-cosφ=1, 250Vac-1A-cosφ=0.4, 30Vdc-1A)	
	Low speed/speed reach signal output Note 2)	Open collector output (24Vdc, max. 50mA, output impedance: 33Ω)	
	Upper/lower limit frequency signal output Note 2)	Open collector output (24Vdc, max. 50mA, output impedance: 33Ω)	
	Output for frequency meter/output for ammeter Note 3)	Analog output. 1mAdc full-scale DC ammeter or 7.7Vdc-1mA voltmeter	
	Pulse train frequency output	Open collector output (24Vdc, max. 50mA)	
	Communication function	RS-485 standard 2-channel equipped (connector: modular 8P)	
	Operating environments	Indoor use. Altitude: 3000m or less (current reduction necessary if 1000m or more.) Place not exposed to direct sunlight and free of corrosive and explosive gases.	
	Environments	Ambient temperature	-10 to +60°C (Remove the upper cover if 40°C or more, max. 60°C) Note 4:
Storage temperature		-25 to +70°C	
Relative humidity		20 to 93% (free from condensation)	
Vibration		5.9m/s² (0.6G) or less (10 to 55Hz) (Compliant with JIS C0040)	

Note 1: 16 contact input terminals (of which 8 are options) are programmable contact input terminals, and they make it possible to arbitrarily select from 80 types of signals.

Note 2: Programmable ON/OFF output terminals make it possible to arbitrarily select from 180 types of signals.

Note 3: Programmable analog output terminals make it possible to arbitrarily select from 50 types of signals.

Note 4: When using inverters where the ambient temperature will rise above 50°C or 45°C, remove the upper cover and operate each inverter at a current lower than the rated one.

Note 5: This function protects inverters from overcurrent due to output circuit ground fault.

External dimensions

■ 200 V class -0.4 to 75 kW, 400 V class -0.75 to 110 kW model

Figure A

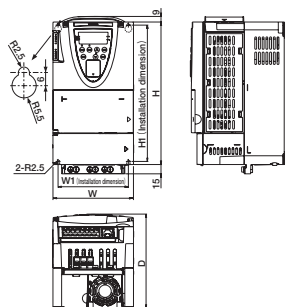


Figure B

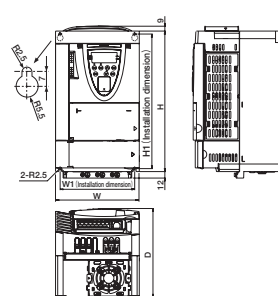


Figure C

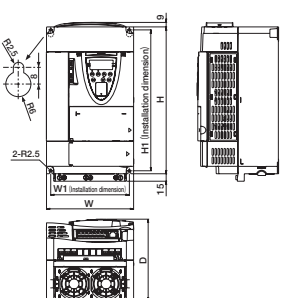


Figure D, E

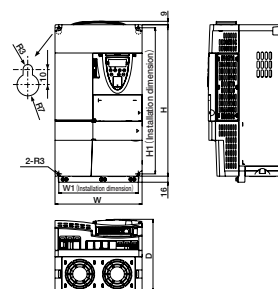


Figure F

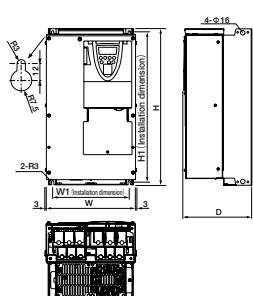


Figure G

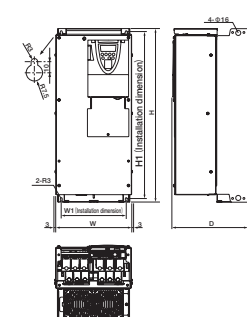


Figure H

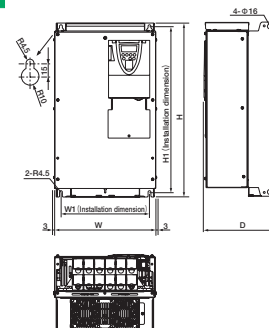


Figure I

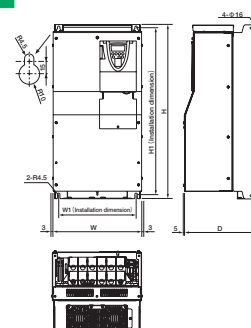
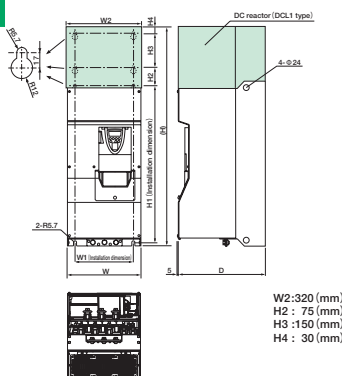


Figure J



Input Voltage Class	Applicable Motor (kW)	Inverter Type	Dimensions (mm)					External Dimension Drawing	Approx. Weight (kg)
			W	H	D	W1	H1		
200V	0.4	VFPS1-2004PL							3
	0.75	VFPS1-2007PL						A	3
	1.5	VFPS1-2015PL	130	230	152	114	220	A	3
	2.2	VFPS1-2022PL						B	4
	3.7	VFPS1-2037PL	155	260	164	138	249	B	4
	5.5	VFPS1-2055PL	175	295	164	158	283	C	5.5
	7.5	VFPS1-2075PL	210	295	191	190	283	D	7.5
	11	VFPS1-2110PM							14
	15	VFPS1-2150PM	230	400	191	210	386	E	14
	18.5	VFPS1-2185PM							21
	22	VFPS1-2220PM	240	420	212	206	403	F	21
	30	VFPS1-2300PM							41
	37	VFPS1-2370PM	320	550	242	280	525	H	41
	45	VFPS1-2450PM							41
	55	VFPS1-2550P							
	75	VFPS1-2750P	310	680 (920)	370	250	650	J	59 (87)
400V	0.75	VFPS1-4007PL							3
	1.5	VFPS1-4015PL							3
	2.2	VFPS1-4022PL	130	230	152	114	220	A	3
	3.7	VFPS1-4037PL	155	260	164	138	249	B	4
	5.5	VFPS1-4055PL	175	295	164	158	283	C	5.5
	7.5	VFPS1-4075PL							5.5
	11	VFPS1-4110PL	210	295	191	190	283	D	8
	15	VFPS1-4150PL	230	400	191	210	386	E	13
	18.5	VFPS1-4185PL							16
	22	VFPS1-4220PL	240	420	212	206	403	F	21
	30	VFPS1-4300PL							29
	37	VFPS1-4370PL	240	550	242	206	529	G	29
	45	VFPS1-4450PL							48
	55	VFPS1-4550PL	320	630	290	280	605	I	48
	75	VFPS1-4750PL							48
	90	VFPS1-4900PC							
	110	VFPS1-4110KPC	310	680 (920)	370	250	650	J	59 (89)

Note : Value in () includes attached DC reactor.

External dimensions

■ 200 V class -90 kW, 400 V class -132 to 630 kW model

Figure K

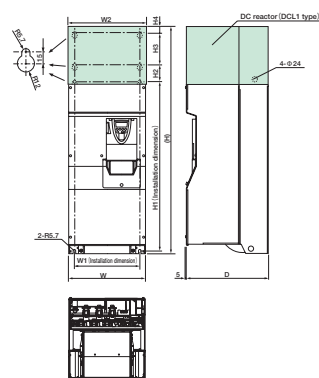


Figure L

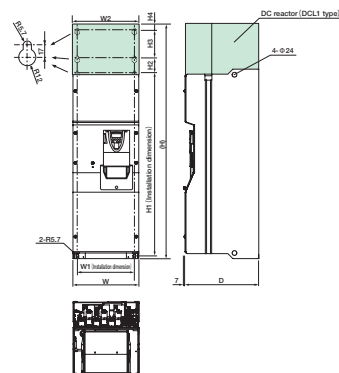


Figure M

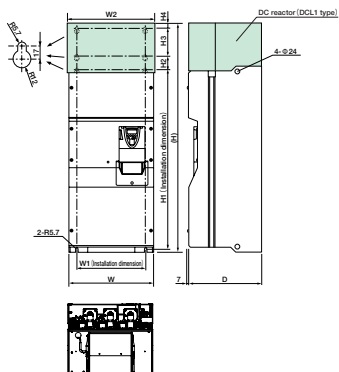


Figure N

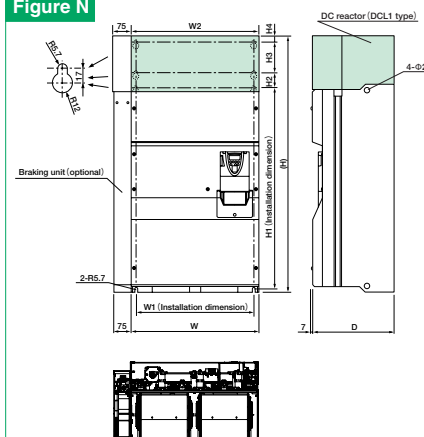


Figure O

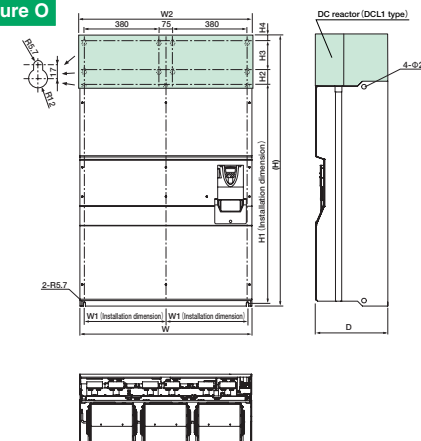
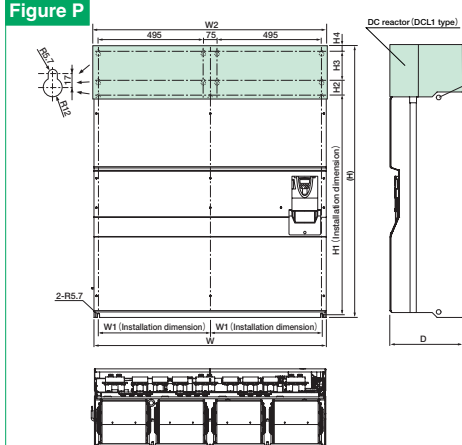


Figure P



Input Voltage Class	Applicable Motor (kW)	Inverter Type	Dimensions (mm)									External Dimension diagram	Approx. Weight (kg)
			W	H	D	W1	H1	W2	H2	H3	H4		
200V	90	VFPS1-2900P	350	782 (1022)	370	298	758	360	72	150	30	K	72 (103)
400V	132	VFPS1-4132KPC	350	782 (1022)	370	298	758	360	72	150	30	K	74 (108)
	160	VFPS1-4160KPC	330	950 (1190)	370	285	920	340	75	150	30	L	82 (118)
	220	VFPS1-4220KPC	430	950 (1190)	370	350	920	440	75	150	30	M	104 (161)
	250	VFPS1-4250KPC	585	950 (1190)	370	540	920	595	75	150	30	N	134 (194)
	280	VFPS1-4280KPC											136 (204)
	315	VFPS1-4315KPC											215 (302)
	400	VFPS1-4400KPC	880	1150 (1390)	370	418	1120	890	75	150	30	O	225 (330)
	500	VFPS1-4500KPC											
		630	VFPS1-4630KPC	1110	1150 (1390)	370	533	1120	1120	75	150	30	P

Note : The value in parentheses includes attached DC reactor.

Standard connection diagrams

■ Standard connection diagram : Sink logic (common : CC)

Main circuit power supply

200V class:

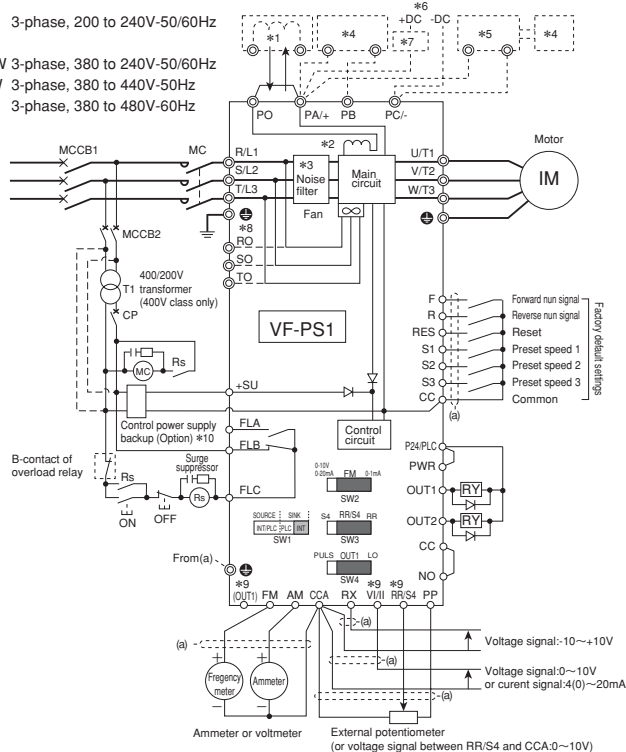
0.4~90kW 3-phase, 200 to 240V-50/60Hz

400V class:

0.75 to 110kW 3-phase, 380 to 240V-50/60Hz

132 to 630kW 3-phase, 380 to 440V-50Hz

3-phase, 380 to 480V-60Hz



*1 : The inverter is shipped with the terminals PO and PA/+ shorted with a bar (200V-45kW or smaller, 400V-75kW or smaller).

Remove this shorting bar when installing a DC reactor (DCL). For 200V-55kW or more, and 400V-90kW or more models, be sure to install the DC reactor.

*2 : The DC reactor is built in for models 200V-11kW~45kW and 400V-18.5kW~75kW.

*3 : The noise filter is built in for models 200V-45kW or smaller and all of 400V.

*4 : External braking resistor (option). Dynamic braking drive circuit built-in (GTR7) as standard for models 220kW or smaller.

*5 : Power generation braking Unit (option). When the external braking resistor (optional) is used on 250kW or more models, the separate power braking unit (optional) is required.

*6 : To supply a DC power, connect the cables to the PA/+ and PA/- terminals.

*7 : If want to use DC power supply to operate the inverter (200V: 18.5kW or more, 400V: 22kW or more), be sure to contact your supplier customer support center, because an inrush current limiting circuit is required in such a case.

*8 : For models 200V-90kW and 400V-132kW or larger, three-phase power input is necessary to drive the fan if you want to use a DC power supply.

*9 : The functions assigned to terminals OUT1, VI/I and RR/S4 can be switched by changing parameter settings.

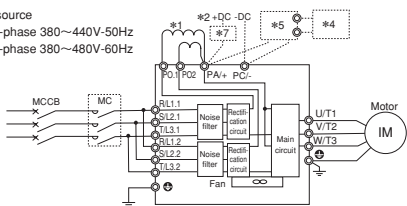
*10 : To supply control power from an external power supply for backing up the control power supplied from the inverter, an optional control power backup device (CPS002Z) is required. In such a case, the backup device is used at the same time with the internal power supply of the inverter. The optional control power backup unit can be used with both 200V and 400V models.

*11 : The rating of 400V-500 and 630kW have the double terminals of R/L1, S/L2, T/L3 for power input, and PO for DC reactor. Please refer the following figure for the wiring.

Main circuit power source

500~630kW Three-phase 380~440V-50Hz

Three-phase 380~480V-60Hz



■ Standard connection diagram : Source logic (common : P24)



Terminal functions

■ Main circuit terminal

Terminal Symbol	Terminal Function
⊕	Grounding terminal for inverter casing
R/L1, S/L2, T/L3	200V class: 0.4~90kW Three-phase 200~240V-50/60Hz 400V class: 0.75~110kW Three-phase 380~480V-50/60Hz 132~630kW Three-phase 380~440V-50Hz Three-phase 380~480V-60Hz (500 and 630kW have the double terminals)
U/T1, V/T2, W/T3	Connect to a (3-phase induction) motor.
PA/+, PB	Connect a braking resistor. (For the optional dynamic braking unit, connect it between PA/+ and PC/-) Change the parameters P_b , P_{b-} and P_{bCP} if necessary. 250kW models and smaller are not equipped with terminal PB. If you are using such a model and you wish to use a braking resistor, you will need to purchase a braking unit separately.
PC/-	This is a negative potential terminal in the internal DC main circuit. DC common power can be input across the PA/+ terminals (positive potential).
PO, PA/+	Terminals for connecting a DC reactor (DCL: optional external device). Shorted by a short bar when shipped from the factory (200V: 45kW or smaller, 400V: 75kW or smaller). Before installing DCL, remove the short bar. (500 and 630kW have the double terminals of PO)
RO, SO, TO	200V class: 90kW 400V class: 132kW~630kW Inverter's cooling power input terminals. When using a DC power supply, connect three-phase power cables.

■ Control circuit terminal

The terminal function settings can be changed according to the application.

Terminal Symbol	Input/output	Function	Electrical Specifications
F	Input	Shorting across F-CC causes forward rotation; open causes deceleration stop. (Across ST-CC is short state.)	Voltage free contact input 24Vdc-5mA or less
R	Input	Shorting across R-CC causes reverse rotation; open causes deceleration stop. (Across ST-CC is short state.)	Can current signal. Choose low current contacts to avoid poor attaching.
RES	Input	Shorting and then opening RES-CC cancels the status held by an inverter protective function. When the inverter is operating normally, shorting and then opening RES-CC produces no effect.	* Sink/source selectable with SW1 Sink input ON : Less than DC10V ON : DC11V or more OFF : DC16V or more OFF : Less than DCSV
S1	Input	Shorting across S1-CC causes preset speed operation.	Note: Even when an external power supply is used (in sink logic mode, i.e., when SINK (PLC) is selected), connect the reference potential-side (0V side) cable from the power supply to the CC terminal.
S2	Input	Shorting across S2-CC causes preset speed operation.	
S3	Input	Shorting across S3-CC causes preset speed operation.	
RR/S4	Input	SW3: When SW4 is in the S4 position, S4 and CC are shorted and preset speed operation is selected.	
P24/PLC	Output	24Vdc power output (when SW1 is in any position other than PLC) 24V internal output terminal	24Vdc-200mA
CC*1	Common to input/output	Digital signal equipotential (0V) terminal for the control circuit and equipotential (0V) terminal for an optional control power supply backup.	—
PP	Output	Analog input setting power output	10Vdc (Permissible load current: 10mA)
PWR*2	Input	If P24/PLC and PWR are short-circuited, the motor is put into a standby state. And if the circuit between them is opened, the motor coasts and stops. These terminals can be used for interlock. This terminal is not a multifunction programmable input terminal. It is a terminal with the power removal safety function that complies with EN954-1 category 3 and IEC/EN61508-1 SIL II.	Regardless of the setting of SW1 ON : DC17V or more OFF : Less than DC2V (OFF: Coast stop)
RR/S4	Input	SW3: Multifunction programmable analog input terminal when SW4 is in the RR position. Standard default setting: 0~10Vdc input and 0~60Hz frequency.	10Vdc (Internal impedance: 30 kΩ)
VI/I	Input	Multifunction programmable analog input. Standard default setting: 0~10Vdc input and 0~60Hz frequency. This terminal can also be used as a 4~20mA (0~20mA) input terminal, if the parameter $F108$ set to 1.	10Vdc (Internal impedance: 30 kΩ) 4~20mA (Internal impedance: 242Ω)
RX	Input	Multifunction programmable analog input. Standard default setting: 0~10Vdc input and 0~60Hz frequency.	10Vdc (Internal impedance: 22 kΩ)
FM	Output	Multifunction programmable analog output. Standard default setting: output frequency Connect a 1mA full-scale ammeter or 7.5Vdc (10Vdc)-1mA full-scale voltmeter. This terminal can also be used as a 0~20mA (4~20mA) terminal, if the parameter $F58$ set to 1 and the SW2 switch is set to OFF.	1mA full-scale DC ammeter or 7.5Vdc-1mA full-scale DC voltmeter 0~20mA (4~20mA) Full-scale DC ammeter
AM	Output	Multifunction programmable analog output. Standard default setting: output current Use this terminal to connect a 1mA full-scale ammeter or 7.5Vdc (10Vdc)-1mA full-scale voltmeter.	1mA full-scale DC ammeter or 7.5Vdc-1mA full-scale DC voltmeter
OUT1	Output	Multifunction programmable open collector output. The default setting is to output a signal when output low speed threshold has been reached. Depending on the SW4 setting, pulses are output with frequencies of 1.0kHz to 43.2kHz. Standard default setting: 3.84kHz	Open collector output 24Vdc-50mA
OUT2	Output	Multifunction programmable open collector output. By default, it is set to output a signal indicating the completion of acceleration or deceleration.	* Sink logic/source logic switchable
NO	Output	Digital output signal equipotential (0V) terminal for the control circuit. It is insulated from the CC terminal.	
CCA*1	Common to input/output	Analog input/output signal equipotential (0V) terminal for the control circuit.	—
+SU	Input	DC power input terminal for operating the control circuit. Connect a control power backup device (optional) between +SU and CC.	Voltage: 24Vdc: 10% Use a power supply with a current rating of 1.1A or more.
FLA FLB FLC	Output	Relay contact output. Contact rating Used to detect the activation of the inverter's protective function. Contact across FLA-FLC is closed and FLB-FLC is opened during protection function operation.	250Vac-2A 30Vdc-1A at resistance load 250Vac-1A cosφ=0.4

*1: Although the CC terminal and the CCA terminal are not insulated, they should be used separately, one for the logic circuit and the other for the analog circuit.

*2: The PWR terminal is not the same as the ST (standby signal input) terminal provided for conventional models. To use the ST function, assign it to a multifunction terminal (F, R, RES or S1 to S4) that is not currently in use.

Example: When assigning the ST function to the S3 terminal.

Set $F110$ to 0, and Set $F117$ to 6.

These settings put the motor into a standby state if S3 and CC are short-circuited, or coast and stop the motor if the circuit between S3 and CC is opened.

For inverter users

When studying how to use our inverters

Notes

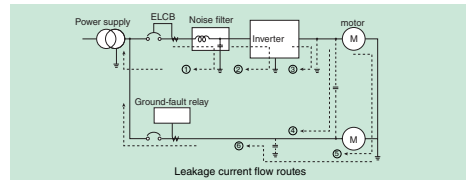
Leakage current

This inverter uses high-speed switching devices for PWM control. When a relatively long cable is used for power supply to an inverter, current may leak from the cable or the motor to the ground because of its capacitance, adversely affecting peripheral equipment. The intensity of such a leakage current depends on the PWM carrier frequency, the lengths of the input and output cables, etc., of the inverter. To prevent current leakage, it is recommended to take the following measures.

[Effects of leakage current]

Leakage current which increases when an inverter is used may pass through the following routes:

- Route (1) ... Leakage due to the capacitance between the ground and the noise filter
 - Route (2) ... Leakage due to the capacitance between the ground and the inverter
 - Route (3) ... Leakage due to the capacitance between ground and the cable connecting the inverter and the motor
 - Route (4) ... Leakage due to the capacitance of the cable connecting the motor and an inverter in another power distribution line
 - Route (5) ... Leakage through the grounding line common to motors
 - Route (6) ... Leakage to another line because of the capacitance of the ground
- Leakage current which passes through the above routes may cause the following trouble.
- Malfunction of a leakage circuit breaker in the same or another power distribution line
 - Malfunction of a ground-relay installed in the same or another power distribution line
 - Noise produced at the output of an electronic device in another power distribution line
 - Activation of an external thermal relay installed between the inverter and the motor, at a current below the rated current



[Measures against effects of leakage current]

The measures against the effects of leakage current are as follows:

- 1) Measures to prevent the malfunction of leakage circuit breakers
 - (1) Decrease the PWM carrier frequency of the inverter. *Note*
 - (2) Use radio-frequency interference-proof ELCBs (manufactured by Toshiba Schneider Inverter Corporation) as ground-fault interrupters in not only the system into which the inverter is incorporated but also other systems. When ELCBs are used, the PWM carrier frequency needs to be increased to operate the inverter.
- (3) When connecting multiple inverters to a single ELCB, use an ELCB with a high current sensitivity or reduce the number of inverters connected to the ELCB.
- 2) Measures against malfunction of ground-fault relay:
 - (1) Decrease the PWM carrier frequency of the inverter. *Note*
 - (2) Install ground-fault relays with a high-frequency protective function (e.g., Toshiba CCR12 type of relays) in both the same and other lines. When ELCBs are used, the PWM carrier frequency needs to be increased to operate the inverter.
- 3) Measures against noise produced by other electric and electronic systems:
 - (1) Separate the grounding line of the inverter from that of the affected electric and electronic systems.
 - (2) Decrease the PWM carrier frequency of the inverter. *Note*
- 4) Measures against malfunction of external thermal relays:
 - (1) Remove the external thermal relay and use the electronic thermal function of the inverter instead of it. (Unapplicable to cases where a single inverter is used to drive more than one motor. Refer to the instruction manual for measures to be taken when thermal relays cannot be removed.)
 - (2) Decrease the PWM carrier frequency of the inverter. *Note*
- 5) Measures by means of wiring and grounding
 - (1) Use a grounding wire as large as possible.
 - (2) Separate the inverter's grounding wire from that of other systems or install the grounding wire of each system separately to the grounding point.
 - (3) Ground (shield) the main circuit wires with metallic conduits.

- (4) Use the shortest possible cables to connect the inverter to the motor.
- (5) If the inverter has a high-attenuation EMI filter, turn off the grounding capacitor detachment switch to reduce the leakage current. Note that doing so leads to a reduction in the noise attenuating effect.

Note) In the case of this inverter, the PWM carrier frequency can be decreased to 1.0kHz or 2.5kHz. However, that it should not be set to less than 2.0kHz during vector control. Decreasing the carrier frequency results in an increase in electromagnetic noise from the motor.

Ground fault

Before beginning operation, thoroughly check the wiring between the motor and the inverter for incorrect wiring or short circuits. Do not ground the neutral point of any star-connected motor.

Radio interference

[Noise produced by inverters]

Since this inverter performs PWM control, it produces noise and sometimes affects nearby instrumental devices, electrical and electronic systems, etc. The effects of noise greatly vary with the noise resistance of each individual device, its wiring condition, the distance between it and the inverter, etc.

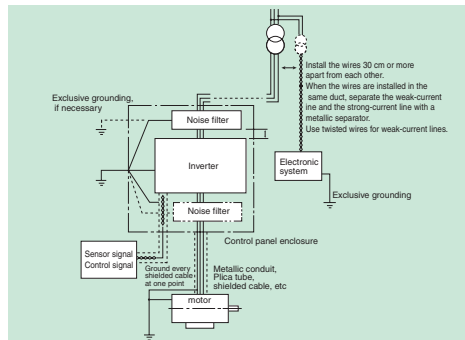
[Measures against noises]

According to the route through which noise is transmitted, the noises produced by an inverter are classified into transmission noise, induction noise and radiation noise.

[Examples of protective measures]

- Separate the power line from other lines, such as weak-current lines and signal lines, and install them apart from each other.
- Install a noise filter in each inverter. It is effective for noise prevention to install noise filters in other devices and systems, as well.
- Shield cables and wires with grounded metallic conduits, and cover electronic systems with grounded metallic cases.
- Separate the power distribution line of the inverter from that of other devices and systems.
- Install the input and output cables of the inverter apart from each other.
- Use shielded twisted pair wires for wiring of the weak-current and signal circuits, and always ground one of each pair of wires.
- Ground the inverter with grounding wires as large and short as possible, separately from other devices and systems.

On 200V 0.4 to 7.5kW and 400V 0.75 to 75kW models, noise can be greatly reduced as they have a built-in EMI noise filter on their input side.



Power factor improvement capacitors

Do not install a power factor improvement capacitors on the input or output side of the inverter.

Installing a power factor improvement capacitor on the input or output side causes current containing harmonic components to flow into the capacitor, adversely affecting the capacitor itself or causing the inverter to trip. To improve the power factor, install an input AC reactor or a DC reactor (optional) on the primary side of the inverter.

Installation of input AC reactors

These devices are used to improve the input power factor and suppress high harmonic currents and surges. Install an input AC reactor when using this inverter under the following conditions:

- (1) When the power source capacity is 500kVA or more, and when it is 10 times or more greater than the inverter capacity.
- (2) When the inverter is connected the same power distribution system as a thyristor-committed control equipment.
- (3) When the inverter is connected to the same power distribution system as that of distorted wave-producing systems, such as arc furnaces and large-capacity inverters.

When wiring the inverter

Wiring precautions

Installing a molded-case circuit breaker (MCCB)

- (1) Install a molded-case circuit breaker (MCCB) on the inverter's power supply input to protect the wiring.
- (2) Avoid turning the molded-case circuit breaker on and off frequently to turn on/off the motor.
- (3) To turn on/off the motor frequently, close/break the control terminals F (or R)-CC.

Installing a magnetic contactor [MC] [primary side]

- (1) To prevent an automatic restart after the power interruption or overload relay has tripped, or actuation of the protective circuit, install an electro-magnetic contact in the power supply.
- (2) The inverter is provided with a failure detection relay (FL), so that, if its contacts are connected to the operation circuit of the magnetic contactor on the primary side, the magnetic contactor will be opened when the protective circuit of the inverter is activated.
- (3) The inverter can be used without a magnetic contactor. In this case, use an MCCB (equipped with a voltage tripping device) for opening the primary circuit when the inverter protective circuit is activated.
- (4) Avoid turning the magnetic contactor on and off frequently to turn on/off the motor.
- (5) To turn on/off the motor frequently, close/break the control terminals F (or R)-CC.

Installing a magnetic contactor [MC] [secondary side]

- (1) As a rule, if a magnetic contactor is installed between the inverter and the motor, do not turn of ON/OFF while running. (If the secondary-side contactor is turned of ON/OFF while running, a large current may flow in the inverter, causing inverter damage and failure.)
- (2) A magnetic contactor may be installed to change the motor or change to the commercial power source when the inverter is stopped. Always use an interlock with the magnetic contactor in this situation so that the commercial power supply is not applied to the inverter's output terminals.

External signal

- (1) Use a relay rated for low currents. Mount a surge suppressor on the excitation coil of the relay.
- (2) When wiring the control circuit, use shielded wires or twisted pair cables.
- (3) Because all of the control terminals except FLA, FLB and FLC are connected to electronic circuits, insulate these terminals to prevent them from coming into contact with the main circuit.

Installing an overload relay

- (1) The VF-S11 inverter has an electronic-thermal overload protective function. However, in the following cases, the thermal relay operation level must be adjusted or an overload relay matching the motor's characteristics must be installed between the inverter and the motor.

- (a) When using a motor having a rated current value different from that of the equivalent.
- (b) When driving several motors simultaneously.
- (2) When using the inverter to control the operation of a constant-torque motor (VF motor), change the protective characteristic of the electronic thermal relay according to the setting of the VF motor.
- (3) In order to adequately protect a motor used for low-speed operation, we recommend the use of a motor equipped with an embedded thermal relay.

When changing the motor speed

Application to standard motors

Vibration

When a motor is operated with an industrial inverter, it experiences more vibrations than when it is operated by the commercial power supply. The vibration can be reduced to a negligible level by securing the motor and machine to the base firmly. If the base is weak, however, the vibration may increase at a light load due to resonance with the mechanical system.

Reduction gear, belt, chain

Note that the lubrication capability of a reducer or a converter used as the interface of the motor and the load machine may be affected at low speeds. When operating at a frequencies exceeding 60 Hz or higher, power transmission mechanisms such as reduction gear, belts and chains, may cause problems such as production of noise, a reduction in strength, or shortening of service life.

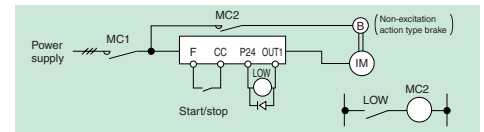
Frequency

Before setting the maximum frequency to 60 Hz or higher, confirm that this operating range is acceptable for the motor.

Application to special motors

Braking motor

When using a braking motor, if the braking circuit is directly connected to the inverter's output terminals, the brake cannot be released because of the lowered starting voltage. Therefore, when using a braking motor, connect the braking circuit to the inverter's power supply side, as shown on the below. Usually, braking motors produce larger noise in low speed ranges.



Gear motor

When using an industrial inverter to drive a gear motor, inquire of the motor manufacturer about its continuous operation range, since low-speed operation of a gear motor may cause insufficient lubrication.

Toshiba Gold Motor (High-efficiency power-saving motor)

Inverter-driven operation of Toshiba Gold Motors is the best solution for saving energy. This is because these motors have improved efficiency, power factor, and noise/vibration reduction characteristics when compared to standard motors.

Pole-changing motor

Pole-changing motors can be driven by this inverter. Before changing poles, however, be sure to let the motor come to a complete stop.

Hight-pole-count motors

Note that high-pole count motors(8 or more poles), which may be used for fans, etc., have higher rated current than 4-pole motors. The current ratings of multipole motors are relatively high. So, when selecting an inverter, you must pay special attention to its current rating so that the current rating of the motor is below that of the inverter.

Single-phase motor

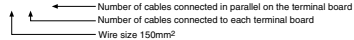
Because single-phase motors are equipped with a centrifugal switch and capacitors for starting, they cannot be driven by an inverter. If only a single-phase, power system is available a 3-phase motor can be driven by using a single-phase input inverter to convert it into a 3-phase 200V output. (A special inverter and a 3-phase motor are required.)

For inverter users

■ Selecting peripheral and wiring sizes devices

Voltage Class	Applicable Motor (kW)	Inverter model	Input current (A)		Molded-case circuit breaker (MCCB) Note 1)2)		Magnetic contactor (MC) Note 1)3)4)5)		Wire size Note 6)7)												Inverter Terminal Screw Size Note 9)	
			Rated current (A)		Operational current (A)		Main circuit				DC terminal		Braking resistor/Braking unit (optional) Note 9)		Ground lead							
							Input terminal (R, S, T)	Output terminal (U, V, W)		AWG							mm ²					
Without Reactor	With Reactor	Without Reactor	With Reactor	Without Reactor	With Reactor	AWG	mm ²	AWG	mm ²	AWG	mm ²	AWG	mm ²	AWG	mm ²	AWG	mm ²					
0.4	VFPS1-2004PL	3.5	2.1	5	5	25	25	14	1.5	14	1.5	14	1.5	14	1.5	14	2.5	M4	M5			
0.75	VFPS1-2007PL	6.1	3.2	10	5	25	25	14	1.5	14	1.5	14	1.5	14	1.5	14	2.5					
1.5	VFPS1-2015PL	11.5	6.4	15	10	25	25	14	1.5	14	1.5	12	1.5	14	1.5	14	2.5					
2.2	VFPS1-2022PL	15	9.3	20	15	25	25	12	1.5	12	1.5	10	2.5	14	1.5	14	2.5					
3.7/4.0	VFPS1-2037PL	26	15.5	30	30	32	25	10	4	10	4	8	6	14	1.5	12	4					
5.5	VFPS1-2055PL	35	22.5	50	40	40	25	8	6	8	6	6	10	14	1.5	10	6					
7.5	VFPS1-2075PL	45	34.5	60	40	50	40	8	10	8	10	4	16	12	2.5	10	10	M6	M8			
11	VFPS1-2110PM	-	53.5	-	75	-	80	4	16	4	16	3	16	10	4	10	16					
15	VFPS1-2150PM	-	72	-	100	-	80	4	25	1	25	8	6	10	10	16						
18.5	VFPS1-2185PM	-	77	-	100	-	80	3	25	3	25	1/0	35	8	10	8	16					
22	VFPS1-2220PM	-	88	-	125	-	125	2	25	2	25	2/0	35	6	16	8	16					
30	VFPS1-2300PM	-	125	-	150	-	125	2/0	50	2/0	50	4/0	70	4	25	6	25					
37	VFPS1-2370PM	-	140	-	175	-	250	3/0	70	3/0	70	250MCM	95	3	35	6	35	M12	M8			
45	VFPS1-2450PM	-	165	-	200	-	250	4/0	70	4/0	70	300MCM	95	2	50	6	35					
55	VFPS1-2550P	-	200	-	250	-	275	3/0 × 2	70 × 2	3/0 × 2	120	4/0 × 2	95 × 2	1/0	50	1/0	70	M10	M10			
75	VFPS1-2750P	-	270	-	350	-	350	4/0 × 2	95 × 2	4/0 × 2	70 × 2	3/0 × 2	95 × 2	1/0	35 × 2	1/0	95					
90	VFPS1-2900P	-	336	-	500	-	500	250MCM × 2	120 × 2	250MCM × 2	95 × 2	300MCM × 2	120 × 2	1/0	50 × 2	1/0	120					
0.75	VFPS1-4007PL	3.7	2.1	5	4	25	25	14	1.5	14	1.5	14	1.5	14	1.5	14	2.5	M5	M5			
1.5	VFPS1-4015PL	5.8	3.8	10	6.3	25	25	14	1.5	14	1.5	14	1.5	14	1.5	14	2.5					
2.2	VFPS1-4022PL	8.2	5.7	14	10	25	25	14	1.5	14	1.5	14	1.5	14	1.5	14	2.5					
3.7/4.0	VFPS1-4037PL	14	8.7	18	14	25	25	12	1.5	12	1.5	10	2.5	14	1.5	14	2.5					
5.5	VFPS1-4055PL	20.5	12.7	32	25	25	25	10	2.5	10	2.5	8	4	14	1.5	12	2.5					
7.5	VFPS1-4075PL	27	16.3	32	25	32	25	10	4	10	4	8	6	14	1.5	12	4					
11	VFPS1-4110PL	36.5	21.5	50	30	40	32	8	6	8	6	6	10	14	1.5	10	6	M6	M8			
15	VFPS1-4150PL	48	33.5	60	40	50	40	6	10	6	10	4	16	12	2.5	10	10					
18.5	VFPS1-4185PL	-	45.5	-	60	-	50	6	10	6	10	4	16	10	2.5	10	10					
22	VFPS1-4220PL	-	50	-	60	-	50	6	10	6	10	4	16	10	4	10	8					
30	VFPS1-4300PL	-	66	-	100	-	80	4	16	4	16	2	25	8	6	10	16					
37	VFPS1-4370PL	-	84	-	100	-	125	3	25	3	25	1	35	8	10	8	16					
45	VFPS1-4450PL	-	105	-	125	-	125	1	35	1	35	2/0	50	6	16	8	16	M12	M10			
55	VFPS1-4550PL	-	120	-	150	-	125	1/0	50	1/0	50	3/0	70	6	16	6	25					
75	VFPS1-4750PL	-	165	-	200	-	250	3/0	70	3/0	70	250MCM	95	3	35	6	35					
90	VFPS1-4800PC	-	170	-	200	-	250	1/0 × 2	70 × 2	1/0 × 2	95	1/0 × 2	95 × 2	1/0	35	2	70					
110	VFPS1-4110KPC	-	200	-	250	-	275	2/0 × 2	95 × 2	2/0 × 2	120	2/0 × 2	95 × 2	1/0	35	2	95					
132	VFPS1-4132KPC	-	240	-	300	-	315	4/0 × 2	95 × 2	4/0 × 2	70 × 2	4/0 × 2	120 × 2	1/0	50	1	95					
160	VFPS1-4160KPC	-	290	-	350	-	350	250MCM × 2	120 × 2	250MCM × 2	95 × 2	4/0 × 2	120 × 2	4/0	70	1	120	M10	M12			
220	VFPS1-4220KPC	-	395	-	500	-	500	350MCM × 2	150 × 2	350MCM × 2	150 × 2	350MCM × 2	150 × 2	4/0	95	2/0	150					
250	VFPS1-4250KPC	-	444	-	700	-	700	250MCM × 3	150 × 2	250MCM × 3	150 × 2	4/0 × 3	185 × 2	300MCM	150	2/0	150					
280	VFPS1-4280KPC	-	495	-	700	-	700	300MCM × 3	150 × 3	300MCM × 3	120 × 3	300MCM × 3	150 × 3	300MCM	150	3/0	120 × 2					
315	VFPS1-4315KPC	-	555	-	700	-	1000	350MCM × 3	150 × 3	350MCM × 3	150 × 3	350MCM × 3	150 × 3	300MCM	150	3/0	120 × 2					
400	VFPS1-4400KPC	-	709	-	1000	-	1000	350MCM × 4	150 × 4	350MCM × 4	120 × 4	350MCM × 3	150 × 4	300MCM × 2	150 × 2	4/0	150 × 2					
500	VFPS1-4500KPC	-	876	-	1200	-	1600	500MCM × 2 × 2 (Note 12)	150 × 2 × 2 (Note 12)	500MCM × 4	185 × 4	500MCM × 4	185 × 4 (Note 11)	300MCM × 2	150 × 2	250MCM	150 × 2	M12	M12			
630	VFPS1-4630KPC	-	1091	-	1600	-	1600	500MCM × 3 × 2 (Note 12)	150 × 3 × 2 (Note 12)	500MCM × 5	185 × 5	500MCM × 4	185 × 4 (Note 11)	300MCM × 2	150 × 2	250MCM	185 × 2					

Note 1) Selections for use of the Toshiba 4-pole standard motor with power supply voltage of 200V/400V-50Hz.
Note 2) Choose the MCCB according to the power supply capacity.
Note 3) For comply with UL and CSA standard, use the fuse certified by UL and CSA.
Note 4) When the motor is driven by commercial power supply switching, for example, use an electromagnetic contactor that is matched to AC-3 class motor rated current.
Note 5) Attach surge killers to the magnetic contactor and exciting coil of the relay.
Note 6) In the case the magnetic contactor (MC) with 2a-type auxiliary contacts is used for the control circuit, raise the reliability of the contact by using 2a-type contacts in parallel connection.
Note 7) The recommended cable size is that of the cable (e.g. 600V class, HJV cable) with continuous maximum permissible temperature of 75°C. Ambient temperature is 40°C or less and the wiring distance is 30m or less.
Note 8) For the control circuit, use shielded wires whose size (cross-section) is 0.75 mm² or more.
Note 9) The screw size of the control terminals is M3.
Note 10) Choose the wire size according to the braking resistor value.
Note 11) On 200 V class 55 kW or more, and 400 V class 90 kW or more models, be sure to install the DC reactor.
Note 12) The recommended cable is 600V class HJV cable with permissible temperature of 90°C.
Note 13) The number refers to a cable composition. For example, in the case of "150 × 2 × 2": 150 × 2 × 2



Selecting the Capacity (model) of the Inverter

selection

Capacity
Refer to the applicable motor capacities listed in the standard specifications.
When driving a high-pole motor, special motor, or multiple motors in parallel, select such an inverter that the sum of the motor rated current multiplied by 1.05 to 1.1 is less than the inverter's rated output current value.

Acceleration/deceleration times
The actual acceleration and deceleration times of a motor driven by an inverter are determined by the torque and moment of inertia of the load, and can be calculated by the following equations.
The acceleration and deceleration times of an inverter can be set individually. In any case, however, they should be set longer than their respective values determined by the following equations.

Acceleration time	$t_a = \frac{(J_M + J_L) \times \Delta N}{9.56 \times (T_M - T_L)} \text{ (sec.)}$	
	$t_d = \frac{(J_M + J_L) \times \Delta N}{9.56 \times (T_B - T_L)} \text{ (sec.)}$	
Conditions	J _M : Moment of inertia of motor (kg·m ²)	
	J _L : Moment of inertia of load (kg·m ²) (converted into value on motor shaft)	
	ΔN : Difference in rotating speed between before and after acc. or dec. (min./min.)	
	T _M : Load torque (N·m) T _L : Motor rated torque × 1.1 (N·m) ... V/f control T _B : Motor rated torque × 1.2 (N·m) ... Vector operation control T _L : Motor rated torque × 0.2 (N·m) (When a braking resistor or a braking resistor unit is used) (Motor rated torque × 0.8-1.0 (N·m))	

Allowable torque characteristics

When a standard motor is combined with an inverter to perform variable speed operation, the motor torque rises slightly higher than it normally does during commercial power supply operation. This is because the inverter output voltage has a sinusoidal (approximate) PWM waveform. In addition, the cooling becomes less effective at low speed, so the torque must be reduced according to the frequency.

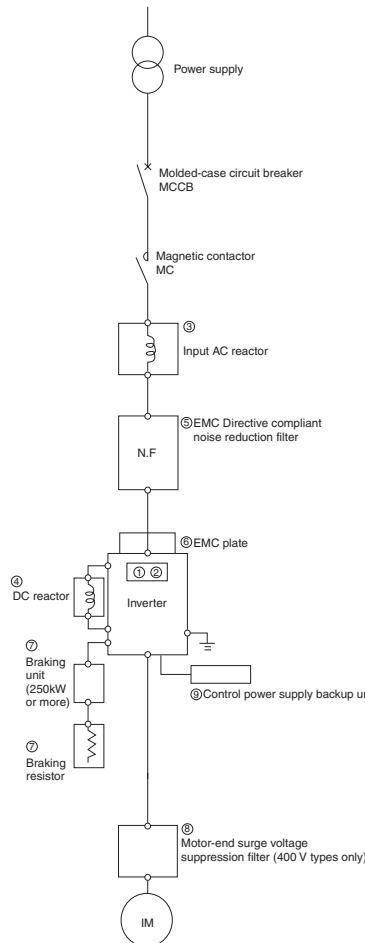
When constant-torque operation must be performed at low speeds, use a Toshiba VF motor designed specifically for use with inverters.

Starting characteristics

When a motor is driven by an inverter, its operation is restricted by the inverter's overload current rating, so the starting characteristic is different from those obtained from commercial power supply operation.

Although the starting torque is smaller with an inverter than with the commercial power supply, a high starting torque can be produced at low speeds by adjusting the V/f pattern torque boost amount or by employing vector control. When a larger starting torque is necessary, select an inverter with a larger capacity and examine the possibility of increasing the motor capacity.

Peripheral devices



■ Built-in options

No.	Name	Function/Purpose, etc.	Refer to
①	Expanded terminal block card	This option is convenient for adding on special functions. (Type : ETB003Z, ETB004Z)	P23
	CC-Link communications card	This option enables CC-Link communications with a host controller or other PLC. (Type : CCL001Z)	
	DeviceNet communications card	This option enables DeviceNet communications with a host controller or other PLC. (Type : DEV002Z)	
	PROFIBUS communications card	This option enables PROFIBUS communications with a host controller or other PLC. (Type : PDP002Z)	
	LowWovex® communications card	This option enables LowWovex® communications with a host controller or other PLC. (Type : LIU006Z)	
	BACnet® communications card	This option enables BACnet® communications with a host controller or other PLC. (Type : BCN001Z)	
②	Metasys® N2 communications card	This option enables Metasys® communications with a host controller or other PLC. (Type : MT001Z)	
	APOGEE® FLN communications card	This option enables APOGEE® FLN communications with a host controller or other PLC. (Type : APG001Z)	
③	PG feedback card (complementary output/line driver output)	Higher performance operation is possible by combining with a motor equipped with a sensor. (Type : VEC004Z, VEC005Z, VEC007Z)	

■ External options

Built-in options

Here are the internal devices optionally available. There are two types of optional devices: Add-on type and Plug-in type.

Table of optional devices

Option name	Function, purpose	Model	Type of installation
Expansion terminal function	Expansion I/O card1	ETB003Z	Add-on
	Expansion I/O card2	ETB004Z	Add-on
Communication function	CC-Link communication card	CCL001Z	Add-on
	DeviceNet communication card	DEV002Z	Add-on
	PROFIBUS-DP communication card	PDP002Z	Add-on
	LonWorks communication card	LIU006Z	Add-on
	BAC net communication card	BCN001Z	Add-on
	Metasys N2 communication card	MTS001Z	Add-on
	APOGEE FLN communication card	APG001Z	Add-on
PG feedback	Push-pull 12V	VEC004Z	Plug-in
	Push-pull 15V	VEC005Z	Plug-in
	RS422-5V	VEC007Z	Plug-in

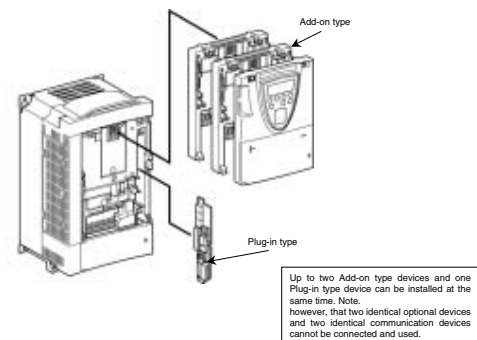
Up to two Add-on type devices and one Plug-in type device can be installed at the same time. Note, however, that two identical optional devices and two identical optional communication devices cannot be connected and used.

Function of Expansion I/O card

Model	ETB003Z	ETB004Z
Multifunction programmable contact input	Multifunction programmable contact input : 4 points No-voltage contact input (24Vdc-5mA or less) Sink logic input (at a common voltage of 24V) Source logic input ON: Less than 10Vdc ON: 11Vdc or more OFF: 16Vdc or more OFF: Less than 5Vdc	
Multifunction programmable open collector output	Multifunction programmable open collector output : 2 points Driving current: Max. 50mA when an external power source is used Max. 20mA when the internal power source is used Driving voltage: 12V (min) to 30V (max)	
Multifunction programmable relay contact output	1C contact configuration 250Vac-2A (cosφ=1), 250Vac-1A (cosφ=0.4), 30Vdc-1A	
Differential current input	Disable	Current input: 20mA or less Voltage input: Differential voltages 5V or less, -10V or more, +10V or less
Analog input	Disable	Current input: 20mA or less Voltage input: 0V to 10V
Monitor output	Disable	Voltage output: -10V to 10V, 0V to 10V Current output: 0mA to 20mA
Pulse train input	Disable	Input pulse specifications Voltage: Max. 5V Current: Max. 15mA Frequency: Max. 30kHz Duty: 50±10%
External thermal trip input	Resistance between TH+ and TH- Error: Approx. 70Ω or less or approx. 3kΩ or more Recovery from error: Approx. 1.6kΩ	
24V power output	24Vdc - 60mA max	
-10V power output	-10Vdc -10mA	
Contact input common terminal	Common terminals for contact input	

How to install

Add-on type devices and insertion type devices are installed in different ways. Install them correctly, as shown in the figures below.



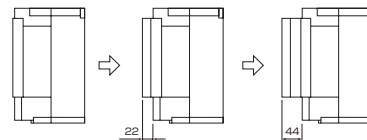
Function of PG feedback card

Model	VEC004Z, VEC005Z	VEC007Z
Sensor vector control operation	Speed control operation: Zero-speed - 120% torque Speed control range: 1:1000 (1000ppr PG)	
PG method	Complementary method, open collector method	Line drive method
PG cable length	Max. 100m (complementary method)	Max. 30m
PG supply power	VEC004Z: 12V-160mA VEC005Z: 15V-150mA	5V-160mA
Maximum pulse input frequency	300kHz or less * If a two-phase open collector is used, a study needs to be made to determine the derating factor. For details, refer to the operating manual for the optional device. Pulse duty: 50±10%	
Pulse input voltage	12Vdc-24Vdc	
	Line driver (LTC485 or equivalent)	

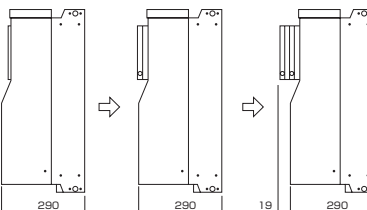
Dimension of depth that installed option

Depending on the capacity, the installation of an Add-on type device may increase the depth of the inverter.

200V 0.4 to 45kW/400V 0.75 to 37kW

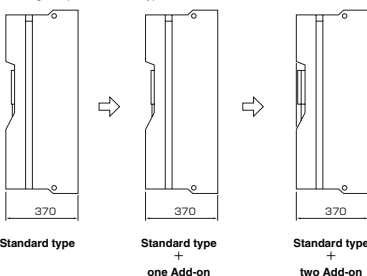


400V 45 to 75kW



200V 55 to 90kW/400V 90 to 630kW

Note: The inverters of these capacities come equipped with an Add-on type option case as standard.
When installing an optional Add-on type device, remove the case.



External options

Voltage class	Applicable motor (kW)	Inverter model	Input AC reactor (ACL)	DC reactor (DCL) (Note 4)	EMC Directive compliant noise reduction filter	Braking resistor (Note 1), 2)	Motor end surge voltage suppression filter
200V class	0.4	VFPS1-2004PL					
	0.75	VFPS1-2007PL	PFL-2005S	DCL-2007		PBR-2007	
	1.5	VFPS1-2015PL					
	2.2	VFPS1-2022PL	PFL-2011S	DCL-2022		PBR-2022	
	3.7	VFPS1-2037PL	PFL-2018S	DCL-2037		PBR-2037	
	5.5	VFPS1-2055PL	PFL-2025S	DCL-2055		PBR3-2055	
	7.5	VFPS1-2075PL		DCL-2110		PBR3-2075	
	11	VFPS1-2110PM	PFL-2050S			PBR3-2110	
	15	VFPS1-2150PM					
	18.5	VFPS1-2185PM	PFL-2100S			PBR3-2150	
	22	VFPS1-2220PM					
	30	VFPS1-2300PM	PFL-2150S			PBR3-2220	
	37	VFPS1-2370PM					
	45	VFPS1-2450PM	PFL-2200S			PBR-222W002	
	55	VFPS1-2550P	PFL-2300S				
	75	VFPS1-2750P	PFL-2400S				
	90	VFPS1-2900P	PFL-2600S				
	0.75	VFPS1-4007PL		DCL-2007 (Note 3)		PBR-2007	MSF-4015Z
400V class	1.5	VFPS1-4015PL					
	2.2	VFPS1-4022PL	PFL-4012S	DCL-2022 (Note 3)		PBR-4037	MSF-4037Z
	3.7	VFPS1-4037PL					
	5.5	VFPS1-4055PL					
	7.5	VFPS1-4075PL	PFL-4025S	DCL-4110		PBR3-4055	MSF-4075Z
	11	VFPS1-4110PL				PBR3-4075	
	15	VFPS1-4150PL		DCL-4220		PBR3-4110	MSF-4150Z
	18.5	VFPS1-4185PL	PFL-4050S			PBR3-4150	MSF-4220Z
	22	VFPS1-4220PL					
	30	VFPS1-4300PL				PBR3-4220	MSF-4370Z
	37	VFPS1-4370PL	PFL-4100S				
	45	VFPS1-4450PL					
	55	VFPS1-4550PL	PFL-4150S			PBR-417W008	MSF-4550Z
	75	VFPS1-4750PL					
	90	VFPS1-4900PC	PFL-4300S				MSF-4750Z
	110	VFPS1-4110KPC					
	132	VFPS1-4132KPC					
	160	VFPS1-4160KPC	PFL-4400S			DGP600W-B2 [DGP600W-C2]	MSL-4215T
400V class	220	VFPS1-4220KPC	PFL-4600S			DGP600W-B3 [DGP600W-C3]	MSL-4481T
	250	VFPS1-4250KPC				PB7-4200K (Note 2) DGP600W-B4 [DGP600W-C4]	
	280	VFPS1-4280KPC					
	315	VFPS1-4315KPC	PFL-4800S			PB7-4400K (Note 2) DGP600W-B3 x2 (parallel) [DGP600W-C3 x2 (parallel)]	MSL-4759T
	400	VFPS1-4400KPC					
	500	VFPS1-4500KPC	PFL-4450S x2 (parallel)			PB7-4400K (Note 2) DGP600W-B4 x2 (parallel) [DGP600W-C4 x2 (parallel)]	MSL-41188T
	630	VFPS1-4630KPC	PFL-4613S x2 (parallel)				

Note 1) Model in square brackets is fitted with top cover.

Note 2) To use a 400V/250kW inverter or larger in combination with an external braking resistor (DGP600 series), a braking unit (PB7) is also needed.

Note 3) These reactors are usable for each of 200V class and 400V class.

Note 4) Be sure to connect DC reactor to 200V-55kW or more and 400V-90kW or more inverter. (Not necessary for DC power input.)

DC reactor

External dimensions diagram

Connection diagram

Fig.A

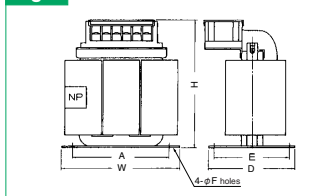


Fig.B

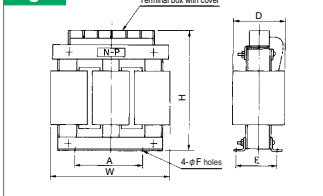


Fig.C

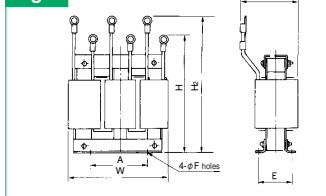


Fig.D

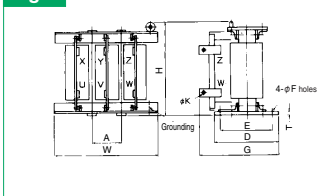


Fig.E

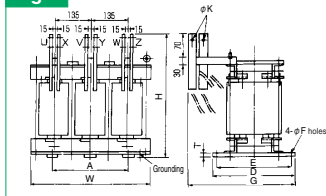
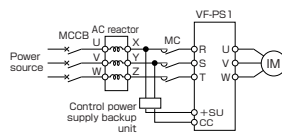
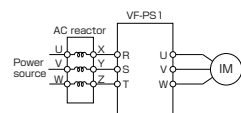
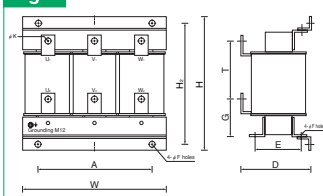
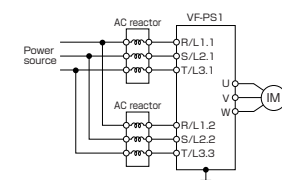


Fig.F



In case of using control power supply
backup unit (option)



For 400V class 500 to 630kW, be sure to connect the AC reactor in parallel.

Model	Rating	Inverter type	Dimensions (mm)										External dimension diagram	Terminals	Approx weight (kg)
			W	H	D	H ₂	A	E	F	G	T	K			
PFL-2006S	3φ-230V-5.5A-50/60Hz	VFPS1-2004PL, 2007PL	105	115	725	—	90	55	5	—	—	—	A	Terminal block M3.5	1.2
PFL-2011S	3φ-230V-11A-50/60Hz	VFPS1-2015PL, 2022PL	130	140	85	—	115	60	5	—	—	—		Terminal block M4	2.3
PFL-2018S	3φ-230V-18A-50/60Hz	VFPS1-2037PL	130	140	85	—	115	60	5	—	—	—		Terminal block M4	2.5
PFL-2025S	3φ-230V-25A-50/60Hz	VFPS1-2055PL	125	130	100	—	50	83	7	—	—	—	B	Terminal block M6	2.6
PFL-2050S	3φ-230V-50A-50/60Hz	VFPS1-2075PL~VFPS1-2110PM	155	140	115	—	60	95	7	—	—	—		Terminal block M6	3.4
PFL-2100S	3φ-230V-100A-50/60Hz	VFPS1-2150PM, 2185PM, 2220PM	230	210	150	—	60	90	8	—	—	—		Terminal block MB	8.2
PFL-2150S	3φ-230V-150A-50/60Hz	VFPS1-2300PM, 2370PM	175	220	160	290	60	110	8	—	—	—	C	Ring terminal 60-10	11.3
PFL-2200S	3φ-230V-200A-50/60Hz	VFPS1-2450PM	195	240	170	320	65	115	10	—	—	—		Ring terminal 80-10	15.1
PFL-2300S	3φ-230V-300A-50/60Hz	VFPS1-2550P	235	280	200	370	75	128	10	—	—	—		Ring terminal 150-10	23.1
PFL-2400S	3φ-230V-400A-50/60Hz	VFPS1-2750P	260	330	230	—	90	200	12	300	9	13	D	φ13	30
PFL-2600S	3φ-230V-600A-50/60Hz	VFPS1-2900P	440	465	290	—	280	250	15	445	12	18	E	φ18	50
PFL-4012S	3φ-460V-12.5A-50/60Hz	VFPS1-4007PL~VFPS1-4037PL	125	130	95	—	50	79	7	—	—	—	B	Terminal block M4	2.3
PFL-4026S	3φ-460V-25A-50/60Hz	VFPS1-4055PL~VFPS1-4110PL	155	155	110	—	50	94	7	—	—	—		Terminal block M6	4.9
PFL-4050S	3φ-460V-50A-50/60Hz	VFPS1-4150PL, 4185PL, 4220PL	155	165	140	—	50	112	7	—	—	—		Terminal block MB	6.6
PFL-4100S	3φ-460V-100A-50/60Hz	VFPS1-4300PL, 4370PL, 4450PL	235	250	170	—	75	105	10	—	—	—	C	Ring Terminal 80-10	17.6
PFL-4150S	3φ-460V-150A-50/60Hz	VFPS1-4450PL, 4750PL	235	280	190	360	75	115	10	—	—	—		Ring Terminal 80-10	20.3
PFL-4300S	3φ-460V-300A-50/60Hz	VFPS1-4900KPC, 4110KPC	260	380	230	—	90	200	12	280	9	13	D	φ13	38
PFL-4400S	3φ-460V-400A-50/60Hz	VFPS1-4132KPC, 4160KPC	260	380	230	—	90	200	12	300	9	13		φ13	42
PFL-4800S	3φ-460V-600A-50/60Hz	VFPS1-4220KPC	440	465	290	—	280	250	15	445	12	18		φ18	75
PFL-4800S	3φ-460V-800A-50/60Hz	VFPS1-4250KPC~VFPS1-4400KPC	440	540	290	—	280	250	15	445	12	18	E	φ18	90
PFL-4450S	3φ-480V-450A-50/60Hz	VFPS1-4500KPC Note 1)	320	385	250	340	225	170	11	86	150	13	F	φ13	68
PFL-4613S	3φ-480V-613A-50/60Hz	VFPS1-4630KPC Note 1)	385	440	255	400	300	165	135	130	190	13		φ13	84.5

Note 1) Be sure to connect the AC reactor in parallel.

DC reactor

For 200V class 11 to 45kW and 400V class 18.5 to 75kW, DC reactor is built-in standard. Please use these external options when requiring the further improvement of the power factor and reducing harmonics.

■ External dimensions diagram

Fig.A

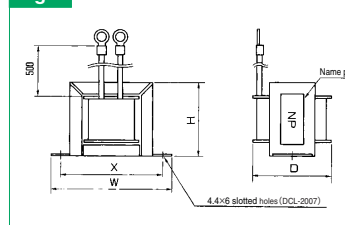


Fig.E

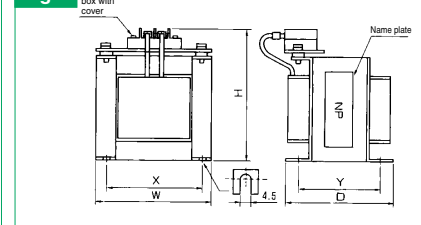


Fig.C

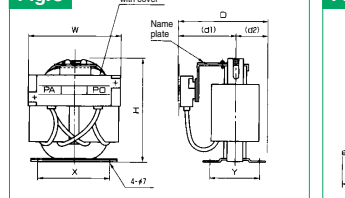
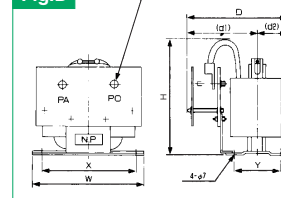
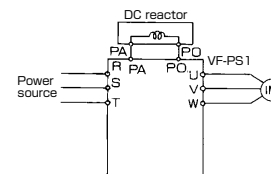


Fig.D



■ Connection diagram



Model	Rated current	Inverter type	Dimensions (mm)							External dimension diagram	Terminal	Approx weight (kg)
			W	H	D	X	Y	d1	d2			
DCL-2007 <small>Note 2)</small>	7A	VFPS1-2004PL, 2007PL	92	65	70	82	—	—	—	A	Ring terminal V2-3.5	1.2
DCL-2022	14A	VFPS1-2015PL, 2022PL	86	110	80	71	64	—	—	B	M4	2.2
DCL-2037	22.5A	VFPS1-2037PL	86	110	85	71	70	—	—			2.5
DCL-2055	38A	VFPS1-2055PL	75	130	140	50	85	85	55	C	M5	1.9
DCL-2110	75A	VFPS1-2075PL~VFPS1-2110PM	100	150	150	65	85	95	55		M6	2.4
DCL-2220	150A	VFPS1-2015PM, 2185PM, 2220PM	117	170	190	90	90	130	60	D	MB	4.3
DCL-2370	225A	VFPS1-2300PM, 2370PM	150	215	200	130	95	135	65		MB	5.9
DCL-2450	300A	VFPS1-2450PM	150	225	230	130	125	150	80	D	M10	7.8
DCL1-2550	316A	VFPS1-2550P, 2750P <small>Note 3)</small>	Refer to external dimension of Inverter.									
DCL1-2750	382A	VFPS1-2900P <small>Note 3)</small>										
DCL-2007 <small>Note 2)</small>	7A	VFPS1-4007PL, 4015PL <small>Note 1)</small>	92	65	70	82	—	—	—	A	Ring terminal V2-3.5	1.2
DCL-2022	14A	VFPS1-4022PL, 4037PL <small>Note 1)</small>	86	110	80	71	64	—	—	B	M4	2.2
DCL-4110	38A	VFPS1-4055PL, 4075PL, 4110PL	95	150	165	70	90	105	60	C	M5	3.0
DCL-4220	75A	VFPS1-4150PL, 4185PL, 4220PL	105	160	185	80	100	120	65		M6	3.7
DCL-4450	150A	VFPS1-4300PL, 4370PL, 4450PL	150	180	225	120	125	145	80	D	MB	9.8
DCL-4750	225A	VFPS1-4550PL, 4750PL	170	215	230	150	125	150	80		MB	11.5
DCL1-4900	243A	VFPS1-4900PC, 4110KPC <small>Note 3)</small>	Refer to external dimension of Inverter.									
DCL1-4110K	290A	VFPS1-4132KPC <small>Note 3)</small>										
DCL1-4132K	351A	VFPS1-4160KPC <small>Note 3)</small>										
DCL1-4160K	486A	VFPS1-4220KPC <small>Note 3)</small>										
DCL1-4200K	575A	VFPS1-4250KPC <small>Note 3)</small>										
DCL1-4280K	702A	VFPS1-4280KPC, 4315KPC <small>Note 3)</small>										

Note 1) These reactors are usable for each of 200V class and 400V class.

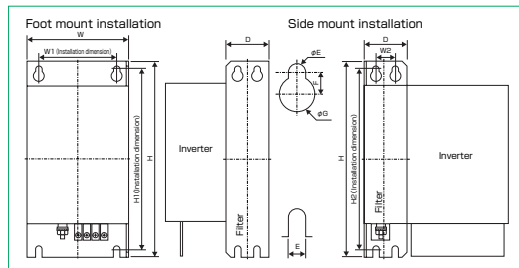
Note 2) Please modify the terminal according to size of inverter main terminal.

Note 3) Be sure to connect DC reactor to 200V-55kW or more and 400V-90kW or more inverter.

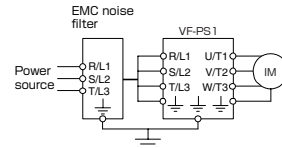
For 200V class 0.4 to 7.5kW and 400V class 0.75 to 630kW, EMC noise filter is built-in standard. Please use these external options depended on the length of the cable between inverter and motor.

Inverter type	Requirements		Conducted noise IEC61800-3 category C2 (EN55011 classA Group1)	Conducted noise IEC61800-3 category C3 (EN55011 classA Group2)
	PWM carrier frequency (kHz)	Length of motor connecting cable(m)		
VFPS1-2004PL-2022PL	4	10	Built-in filter	—
VFPS1-4007PL-4037PL	16	5		
VFPS1-2037PL-2075PL	4	10	—	Built-in filter
VFPS1-4055PL-4150PL	16	5		
VFPS1-4185PL-4750PL	2.5	25		
	16	25		
VFPS1-4900PC-4630KPC	2.5	50		

(1) Foot mount type EMC noise filter



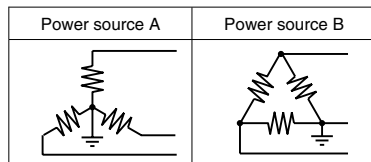
■ Connection diagram



EMC noise filter can be foot mounted and side mounted.

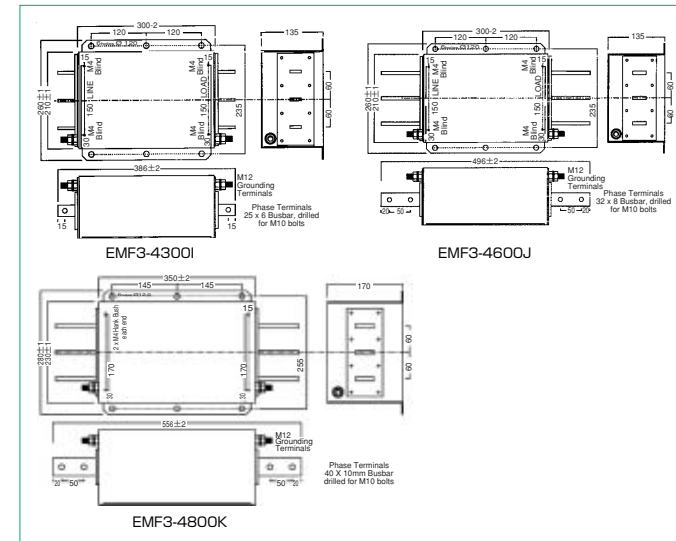
Model	Rated current (A)	Inverter type	Dimensions (mm)											Approx. leakage current (mA) Note 1)		Approx weight (kg)
			W	H	D	W1	H1	W2	H2	E	F	G	Power source A	Power source B		
EMF3-4012A	12	VFPS1-2004PL~2015PL	130	290	39	105	275	—	275	4.5	11	10	5	35	2.5	
		9											70			
EMF3-4026B	26	VFPS1-2022PL~2037PL	155	324	49	130	309	—	309	4.5	11	10	6	42	3.5	
		11											83			
EMF3-4035C	35	VFPS1-2055PL	175	370	59	150	355	—	355	5.5	11	11	4	25	5.0	
		6											44			
EMF3-4046D	46	VFPS1-2075PL	210	380	59	190	365	—	365	5.5	11	11	12	91	6.0	
		VFPS1-4110PL											24	183		
EMF3-4072E	72	VFPS1-210PM,2150PM	230	498.5	62	190	460	—	479.5	6.6	11	12	25	195	11	
		VFPS1-4150PL, 4185PL											52	390		
EMF3-4090F	90	VFPS1-2185PM,2220PM	240	521.5	79	200	502.5	40	502.5	6.6	11	12	36	268	15	
		VFPS1-4220PL											70	535		
EMF3-4092G	92	VFPS1-4300PL,4370PL	240	650	79	200	631	40	631	6.6	11	12	70	535	16	
EMF3-4180H	180	VFPS1-2300PM~2450PM	320	750	119	280	725	80	725	9	18	18	70	537	40	
		VFPS1-4450PL~4750PL											142	1075		

Note 1) These values are referential ones of single piece of EMC noise filter. For 200V class, 200V-60Hz power source. For 400V class, 400V-60Hz power source.

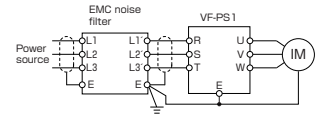


(2) EMC noise filter

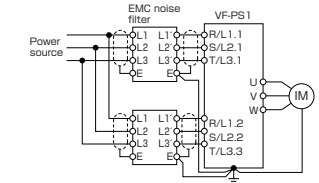
■ External dimensions diagram



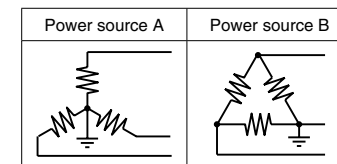
■ Connection diagram



For 200V class 55 to 75kW,
400V class 90 to 400kW



For 400V class 500 to 630kW



Model	Rated current (A)	Inverter type	Terminal		Approx. weight (kg)	Approx. leakage current(mA) Note 2)	
			Main circuit	Grounding		Power source A	Power source B
EMF3-4300I	300	VFPS1-2550P, 2750P	Busbar 25*6 M10	M12	13.2	3	180
		VFPS1-4900PC~4132KPC				5	350
EMF3-4600J	580	VFPS1-2900P, 4160KPC~4280KPC, 4316KPC 4500KPC Note 1), 4630KPC Note 1)	Busbar 32*8 M10	M12	15	5	350
EMF3-4800K	740	VFPS1-4400KPC	Busbar 40*10 M10	M12	25	5	350

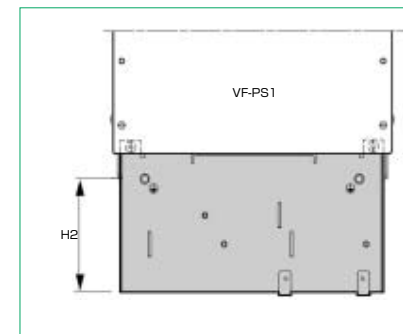
Note 1) Be sure to connect the EMC noise filter in parallel.

Note 2) These values are referential ones of single piece of EMC noise filter. For 200V class, 200V-60Hz power source. For 400V class, 400V-60Hz power source.

EMC plate

EMC plate is attached in standard for 400V class of WP type up to 18.5kW.

■ External dimensions

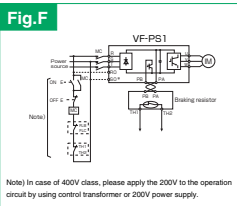
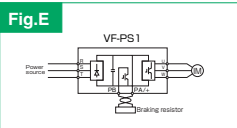
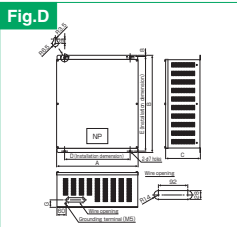
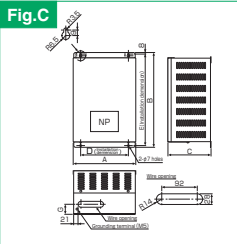
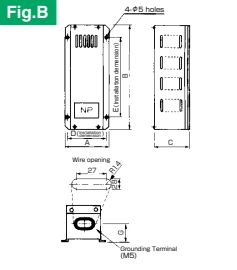
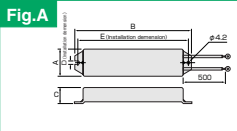


Model	Inverter type	Dimension (mm)
		H2
EMP101Z	VFPS1-2004~2015PL VFPS1-4007~4022PL	55
EMP102Z	VFPS1-2022~2037PL VFPS1-4037PL	
EMP103Z	VFPS1-2055PL, 2075PL VFPS1-4055~4110PL	65
EMP104Z	VFPS1-2110,2150PMP VFPS1-4150, 4185PL	
EMP105Z	VFPS1-2185,2220PMP VFPS1-4220PL	120
EMP106Z	VFPS1-4300,4370PL	
EMP107Z	VFPS1-2300~2450PMP	
EMP108Z	VFPS1-4450~4750PL	

The wire clamps and screws are attached to the EMC plate for fixing the shielded cables on the EMC plate.

Braking resistor

External dimensions diagram, Braking resistor (PBR) connection diagram



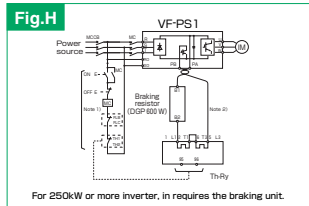
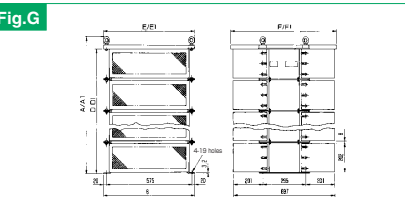
Voltage class	Type	Model Note 1)	Rating Note 2), 3)	Dimensions (mm)						External dimension diagram	Connection diagram	Approx. weight (Kg)
				A	B	C	D	E	G			
200V	Standard	PBR-2007	120W-200Ω	42	182	20	4.2	172	—	A	E	0.28
		PBR-2022	120W-75Ω									
		PBR-2037	120W-40Ω	120	350	190	110	230	150	B	4.5	
		PBR3-2055	200-240W (40Ω-120W×2P)									
		PBR3-2075	150-440W (30Ω-220W×2P)									
		PBR3-2110	100-660W (30Ω-220W×3P)									
		PBR3-2150	7.5Ω-880W (30Ω-220W×4P)	248	430	200	190	414	47	C	5.5	
		PBR3-2220	3.3Ω-1760W (27Ω-220W×8P)									
		PBR-222W002	20-2200W(20Ω-220W×10P)									
		200W class	PBR-202W □□□									40Ω, 75Ω-240W
	500W class	PBR-208W □□□	15Ω, 20Ω, 40Ω, 75Ω-880W	120	350	190	110	230	150	B	3	
	1.5kW class	PBR-217W □□□	15Ω, 20Ω, 40Ω, 75Ω-1760W									
	2.5kW class	PBR-226W □□□	20, 33Ω, 75Ω, 100, 150, 200, 400-2640W	297	445	200	220	429	47	C	14	
	3.5kW class	PBR-235W □□□	3.3Ω, 7.5Ω, 15Ω, 20Ω-3520W									
	5kW class	PBR-252W □□□	20, 3.3Ω, 7.5Ω, 15Ω-5280W	520	616	220	420	600	47	D	36	
400V	Standard	PBR-2007	120W-120Ω	42	182	20	4.2	172	—	A	E	0.28
		PBR-4037	120W-160Ω									
		PBR3-4055	80Ω-240W (160Ω-120W×2P)	120	350	190	110	230	150	B	4.5	
		PBR3-4075	60Ω-440W (120Ω-220W×2P)									
		PBR3-4110	40Ω-660W (120Ω-220W×3P)									
		PBR3-4150	30Ω-880W (120Ω-220W×4P)									
		PBR3-4220	15Ω-1760W (30Ω-220W×4P2S)	248	430	200	190	414	47	C	13	
		PBR-417W008	8Ω-1760W (16Ω-220W×4P2S)									
		200W class	PBR-402W □□□									160Ω-240W
		500W class	PBR-408W □□□									40Ω, 60Ω, 80Ω, 160Ω-880W
	1.5kW class	PBR-417W □□□	30Ω, 40Ω, 60Ω, 80Ω-1760W	248	430	200	190	414	47	C	16	
	2.5kW class	PBR-426W □□□	8Ω, 15Ω, 30Ω, 40Ω-2640W									
	3.5kW class	PBR-435W □□□	15Ω, 30Ω, 40Ω-3520W	520	616	220	420	429	47	D	19	
	5kW class	PBR-452W □□□	8Ω, 15Ω, 30Ω, 40Ω-5280W									
				520	616	220	420	600	47			36

Note 1) □□□□ in the type-form are numeric character. Please refer the "Selection of braking resistor" in the next page.
 Note 2) The rating shows the synthetic resistor value (Ohm) and the synthetic resistor power (Watt). The word in the parentheses shows the composition of resistor elements.
 Note 3) The allowable continuous regenerative power differs on the resistor value or power tolerance. Please refer the "Selection of braking resistor" in the next page.

Braking resistor (DGP600)

Model		Rating	Dimensions (mm) note 2)				External dimension diagram	Connection diagram	Thermal relay(ThRy) Setting value(A)	Approx. weight (kg)
Standard	With cover Note 1)		A/A1	D/D1	E/E1	F/F1				
DGP600W-B1	DGP600W-C1	1.7Ω-3.4kW	283/303	207/192	620/700	725/780	G	H	46	50
DGP600W-B2	DGP600W-C2	3.7Ω-7.4kW	493/513	417/402	620/700	725/780			44	100
DGP600W-B3	DGP600W-C3	1.9Ω-8.7kW	703/723	627/612	620/700	725/780			71	150
		2.5Ω-10.5kW							65	150
		5Ω-10kW							45	150
DGP600W-B4	DGP600W-C4	1.4Ω-14kW	913/933	837/822	620/700	725/780			110	200
		1.7Ω-10kW							77	200

Note 1) The braking resistors are designed for indoor type. Please use them with drip cover in case of water drop. But please note it is not for water proof protection type.
 Note 2) A,D,E,F are the dimensions of standard type. A1,D1,E1,F1 are the dimensions of those with drip cover type.



Note 1) In case of 400V class, please apply the 200V to the operation circuit by using control transformer or 200V power supply.
 Note 2) Please twist the wire by 10 cm pitch. The distance between resistor power wiring and the control wiring should be over 20 cm.
 Note 3) In case of TOSHIBA thermal relay, please make a short circuit with 8 mm² wire between the 2/T1 and 6/T3 of the thermal relay.

Selection of braking resistor

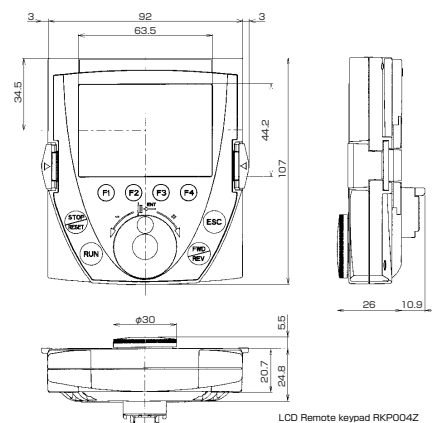
This is used for the quick deceleration, the frequent deceleration stop or shortening the deceleration time at the large inertia load. This resistor consumes the regenerative energy when regenerative braking operation. In case of over 3% ED, please select the allowable continuous regenerative power (Watt) in the following table.

- The continuous regenerative load likes an elevator
- Deceleration stops at large inertia machine
- Frequent deceleration stop by using braking resistors

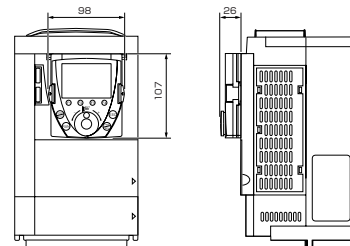
Voltage class	Applicable motor (kW)	Inverter type Note 1)	Model									
			Standard type			High frequency type Note 2)						
			PBR Note 3)	DGP600 Note 4)		PBR						
			Standard	With cover Note 5)	500W class	1.5kW class	2.5kW class	3.5kW class	5kW class	10kW class Note 4)		
200V	0.4	VFPS1-2004PL	PBR-2007 (200Ω-90W)	—	—	PBR-208W075 (75Ω-540W)	—	—	—	—	—	
	0.75	VFPS1-2007PL	—	—	—	PBR-217W075 (75Ω-1600W)	—	—	—	—	—	
	1.5	VFPS1-2015PL	PBR-2022 (75Ω-90W)	—	—	PBR-208W040 (40Ω-570W)	PBR-217W040 (40Ω-1180W)	PBR-226W040 (40Ω-1830W)	—	—	—	
	2.2	VFPS1-2022PL	PBR-2037 (40Ω-90W)	—	—	—	—	—	—	—	—	
	3.7	VFPS1-2037PL	PBR-2055 (20Ω-90W)	—	—	PBR-208W020 (20Ω-570W)	PBR-217W020 (20Ω-950W)	PBR-226W020 (20Ω-1580W)	PBR-235W020 (20Ω-2530W)	—	—	
	5.5	VFPS1-2055PL	PBR-2075 (15Ω-90W)	—	—	—	PBR-217W015 (15Ω-950W)	PBR-226W015 (15Ω-1350W)	PBR-235W015 (15Ω-2330W)	PBR-252W015 (15Ω-3530W)	—	
	7.5	VFPS1-2075PL	PBR-2110 (10Ω-90W)	—	—	—	PBR-217W010 (10Ω-1270W)	PBR-226W010 (10Ω-1550W)	PBR-235W010 (10Ω-1860W)	PBR-252W010 (10Ω-3530W)	—	
	11	VFPS1-2110PM	PBR-2150 (7.5Ω-570W)	—	—	—	—	PBR-226W7R5 (7.5Ω-870W)	PBR-235W7R5 (7.5Ω-1380W)	PBR-252W7R5 (7.5Ω-3210W)	—	
	15	VFPS1-2150PM	—	—	—	—	—	—	—	—	—	
	18.5	VFPS1-2185PM	—	—	—	—	—	—	—	—	—	
	22	VFPS1-2220PM	PBR-2220 (3.3Ω-810W)	—	—	—	—	—	—	PBR-252W3R3 (3.3Ω-1760W)	—	
	30	VFPS1-2300PM	—	—	—	—	—	—	—	—	—	
	37	VFPS1-2370PM	—	—	—	—	—	—	—	—	—	
	45	VFPS1-2450PM	PBR-222W002 (20-1000W)	—	—	—	—	—	—	PBR-226W7R5 x3 (parallel) (2.5Ω-2610W)	DGP600W-B4/C4 (1.7Ω-10kW)	
55	VFPS1-2550P	—	—	—	—	—	—	—	—	—		
75	VFPS1-2750P	—	DGP600W-B1 (1.7Ω-3.4kW)	DGP600W-C1 (1.7Ω-3.4kW)	—	—	—	—	—	—		
90	VFPS1-2900P	—	—	—	—	—	—	—	—	—		
400V	0.75	VFPS1-4007PL	PBR-2007 (200Ω-90W)	—	—	PBR-408W160 (160Ω-570W)	—	—	—	—	—	
	1.5	VFPS1-4015PL	—	—	—	—	—	—	—	—	—	
	2.2	VFPS1-4022PL	PBR-4037 (160Ω-90W)	—	—	PBR-408W080 (80Ω-270W)	PBR-417W080 (80Ω-1690W)	—	—	—	—	
	3.7	VFPS1-4037PL	PBR-4055 (80Ω-90W)	—	—	—	—	—	—	—	—	
	5.5	VFPS1-4055PL	PBR-4075 (60Ω-130W)	—	—	PBR-417W060 (60Ω-1000W)	PBR-426W040 (40Ω-1250W)	PBR-435W040 (40Ω-1900W)	PBR-452W040 (40Ω-2250W)	—	—	
	7.5	VFPS1-4075PL	PBR-4110 (40Ω-130W)	—	—	—	—	—	—	—	—	
	11	VFPS1-4110PL	PBR-4170 (40Ω-130W)	—	—	PBR-417W040 (40Ω-480W)	—	—	—	—	—	
	15	VFPS1-4150PL	PBR-4150 (30Ω-270W)	—	—	—	PBR-426W030 (30Ω-870W)	PBR-435W030 (30Ω-1070W)	PBR-452W030 (30Ω-2700W)	—	—	
	18.5	VFPS1-4185PL	—	—	—	—	—	—	—	—	—	
	22	VFPS1-4220PL	PBR-4220 (15Ω-540W)	—	—	—	—	—	—	PBR-452W015 (15Ω-1740W)	—	
	30	VFPS1-4300PL	—	—	—	—	—	—	—	—	—	
	37	VFPS1-4370PL	—	—	—	—	—	—	—	—	—	
	45	VFPS1-4450PL	PBR-417W008 (80-1000W)	—	—	—	—	—	—	PBR-426W030 x3 (parallel) (10Ω-2610W)	DGP600W-B3/C3 (5Ω-10kW)	
	55	VFPS1-4550PL	—	—	—	—	—	—	—	—	—	
75	VFPS1-4750PL	—	—	—	—	—	—	—	—	—		
90	VFPS1-4900KPC	—	—	—	—	—	—	—	—	—		
110	VFPS1-4110KPC	—	DGP600W-B2 (3.7Ω-7.4kW)	DGP600W-C2 (3.7Ω-7.4kW)	—	—	—	—	—	DGP600W-B3/C3 (2.5Ω-10.5kW)		
132	VFPS1-4132KPC	—	—	—	—	—	—	—	—	—		
160	VFPS1-4160KPC	—	—	—	—	—	—	—	—	—		
220	VFPS1-4220KPC	—	DGP600W-B3 (1.9Ω-8.7kW)	DGP600W-C3 (1.9Ω-8.7kW)	—	—	—	—	—	—		
250	VFPS1-4250KPC	—	PB7-4200K	PB7-4200K	—	—	—	—	—	—		
280	VFPS1-4280KPC	—	DGP600W-B4 (1.4Ω-14kW)	DGP600W-C4 (1.4Ω-14kW)	—	—	—	—	—	—		
315	VFPS1-4315KPC	—	—	—	—	—	—	—	—	—		
400	VFPS1-4400KPC	—	PB7-4400K	PB7-4400K	—	—	—	—	—	—		
500	VFPS1-4500KPC	—	DGP600W-B3 x2 (parallel)	DGP600W-C3 x2 (parallel)	—	—	—	—	—	—		
630	VFPS1-4630KPC	—	PB7-4400K	PB7-4400K	—	—	—	—	—	—		
			DGP600W-B4 x2 (parallel)	DGP600W-C4 x2 (parallel)	—	—	—	—	—	—		

LCD Remote Keypad

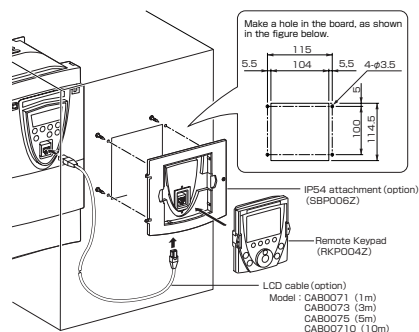
External dimension diagram



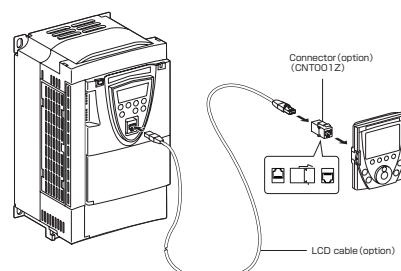
■ Installation on the unit



Installation on the panel

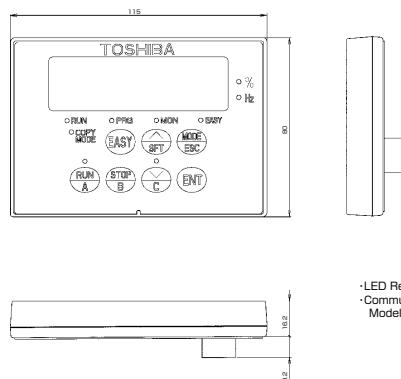


■ Palm top operation

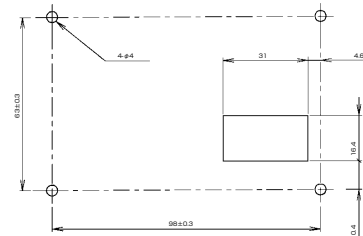


LED Remote Keypad

External dimension diagram



■ Panel cutout dimension

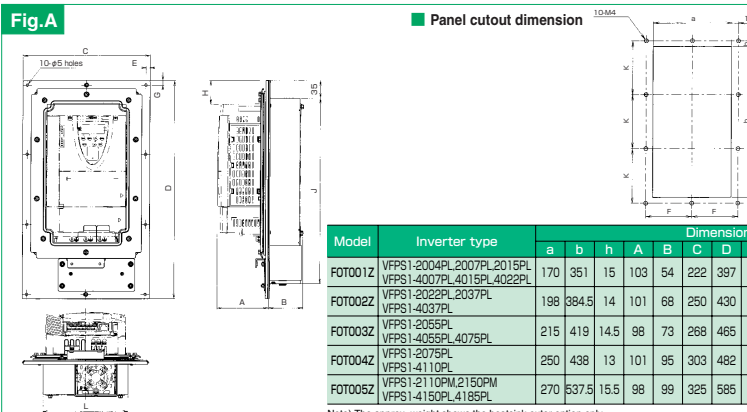


- LED Remote Keypad: RKP002Z
- Communication cable (option)
Model: CAB0011 (1m)
CAB0013 (3m)
CAB0015 (5m)

Heatsink outer option

This options enable the heatsink parts of the backside of inverter that generate much heat to be located at the outside of the panel. This is effective for the small sizing of the totally-enclosed box by reducing the heat values inside the box.

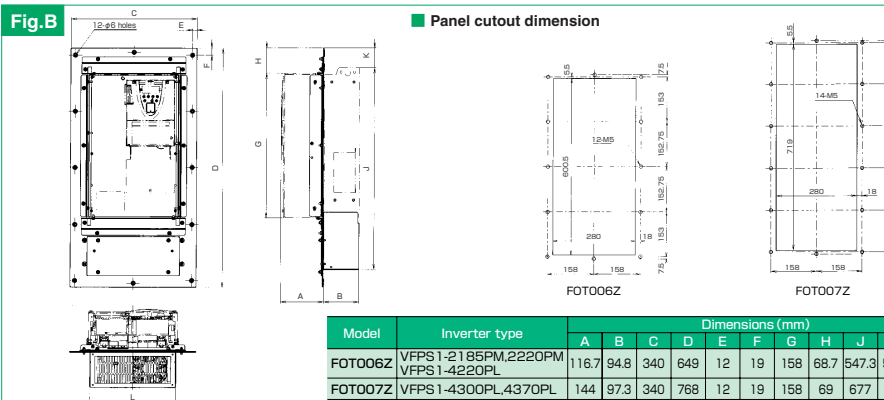
Fig.A



Model	Inverter type	Dimensions (mm)														Approx. Weight (kg)
		a	b	h	A	B	C	D	E	F	G	H	J	K	L	
FOT001Z	VFP5-12004PL/20715PL	170	351	15	103	54	222	397	8.5	102.5	8	47	327.5	127	138.6	2.3
	VFP5-14004PL/4015R_4022PL	170	351	15	103	54	222	397	8.5	102.5	8	47	327.5	127	138.6	2.3
FOT002Z	VFP5-2022PL/2037PL	198	384.5	14	101	68	250	430	8.5	116.5	8.6	46.5	365.5	137.5	166.6	2.5
	VFP5-14037PL	198	384.5	14	101	68	250	430	8.5	116.5	8.6	46.5	365.5	137.5	166.6	2.5
FOT003Z	VFP5-2035PL	215	419	14.5	98	73	268	465	9	125	8.5	46	400.5	145	183.6	3.2
	VFP5-14055PL/4075PL	215	419	14.5	98	73	268	465	9	125	8.5	46	400.5	145	183.6	3.2
FOT004Z	VFP5-12075PL	250	438	13	101	95	303	482	9	142.5	8.5	45.7	419	155	202.2	4.1
	VFP5-14110PL	250	438	13	101	95	303	482	9	142.5	8.5	45.7	419	155	202.2	4.1
FOT005Z	VFP5-21110PL/2150PM	270	537.5	15.5	98	99	325	585	10	152.5	8	45	520.5	189.5	240.2	4.8
	VFP5-21110PL	270	537.5	15.5	98	99	325	585	10	152.5	8	45	520.5	189.5	240.2	4.8

Note) The approx. weight shows the heatsink outer option only.

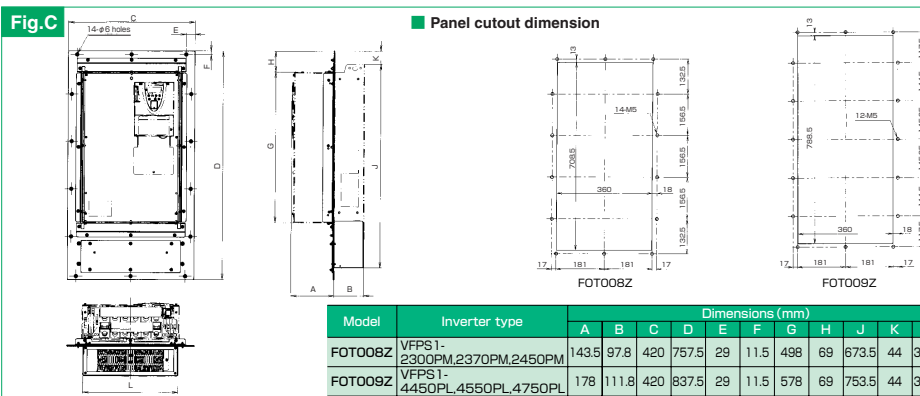
Fig.B



Model	Inverter type	Dimensions (mm)											Approx. weight (kg)
		A	B	C	D	E	F	G	H	J	K	L	
FOT006Z	VFPS1-2185PM,2220PM VFPS1-4220PL	116.7	94.8	340	649	12	19	158	68.7	547.3	53.6	232	4.4
FOT007Z	VFPS1-4300PL,4370PL	144	97.3	340	768	12	19	158	69	677	51	232	5.1

Note) The approx. weight shows the heatsink outer option only.

Fig.C

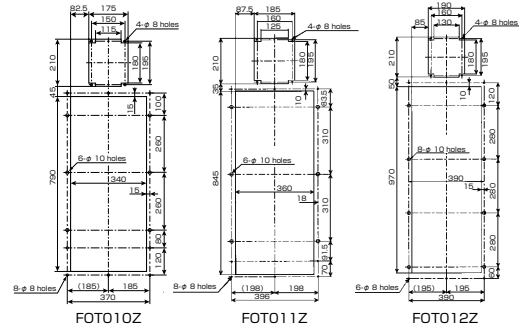


Model	Inverter type	Dimensions (mm)											Approx. weight (kg)
		A	B	C	D	E	F	G	H	J	K	L	
FOT008Z	VFPS1-230PM,2370PM,2450PM	143.5	97.8	420	757.5	29	11.5	498	69	673.5	44	313.2	5.4
FOT009Z	VFPS1-4450PL,4550PL,4750PL	178	111.8	420	837.5	29	11.5	578	69	753.5	44	313.2	5.4

Note) The approx. weight shows the heatsink outer option only.

Fig.D

Panel cutout dimension

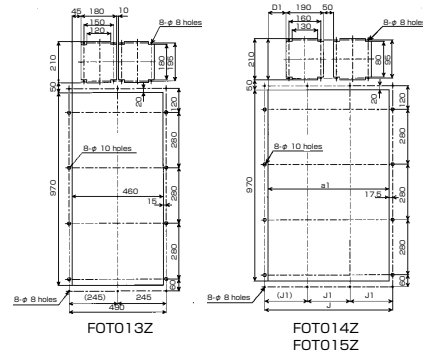


Model	Inverter type	Dimensions (mm)								Approx. weight (kg) (Note)
		A	B	C	D	E	F	G	H	
FOTO10Z	VFPS1-2550P, 2750P VFPS1-4300PC, 4110KPC	245	165	420	850	25	15	230	50	5.1
FOTO11Z	VFPS1-2900P VFPS1-4132KPC	140	230	440	885	22	10	230	23	3.6
FOTO12Z	VFPS1-4160KPC	143	227	442	1061	26	20.5	224.5	85.5	4.3

Note) The approx. weight shows the heatsink outer option only.

Fig.E

Panel cutout dimension



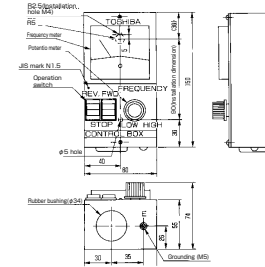
Model	Dimensions (mm)							
	D1	a1	J	J1				
FOTO14Z	90	610	645	215				
FOTO15Z	165	685	720	240				

Model	Inverter type	Dimensions (mm)								Approx. weight (kg) (Note)
		D	B	C	D	E	F	G	H	
FOTO13Z	VFPS1-4220KPC	143	227	542	1061	26	20.5	224.5	85.5	4.4
FOTO14Z	VFPS1-4250KPC, 4280KPC, 4315KPC	143	227	697	1061	26	20.5	224.5	85.5	4.7
FOTO15Z	VFPS1-4250KPC, 4280KPC, 4315KPC with using PB7-4200K	143	227	772	1061	26	20.5	224.5	85.5	4.9

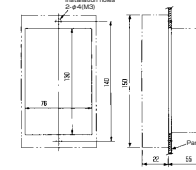
Note) The approx. weight shows the heatsink outer option only.

Operation panel (Model: CBVR-7B1)

External dimension diagram

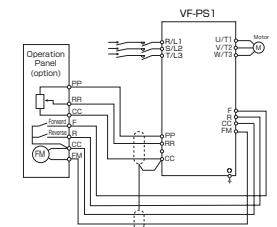


Panel cutout dimension



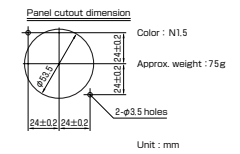
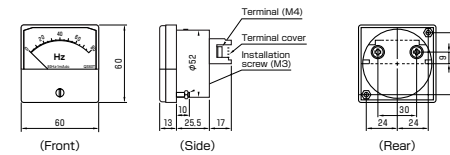
Color : JIS mark 5Y7/1
(Panel front N1.5)
Approx. weight : 0.7kg

Connection diagram



Note) The wire length should be 30m or less the inverter and the operation panel.

Frequency meter <QS-60T (80Hz-1mAdc)>



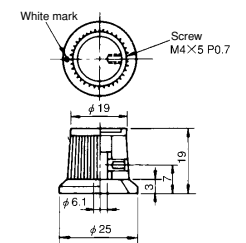
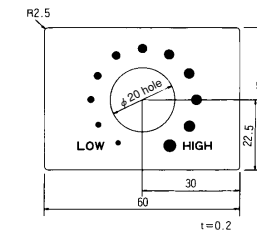
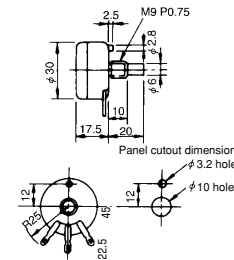
Color : N1.5
Approx. weight : 75g
Unit : mm

FRH-KIT

Potentiometer <RV30YN-20S-B302>

Potentiometer panel

Potentiometer knob <K-3>



Planning

Totally enclosed box type for IP54/UL type 12



Built-in DC reactor

LCD keypad as standard

Built-in EMC noise filter

Line-up

Voltage class	Applicable Motor Output (kW)																
	0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90
3-phase 400V class (IP54)																	

point 1

Totally enclosed box type for IP54/UL type 12

- IP54 protection for direct mounting on a wall

point 2

High-frequency noise reduction

- IP54 product with EN 55011 class A or class B (IEC/EN 61800-3) built-in EMC filters

point 3

Harmonics reduction

- New types of compact and space-saving DC reactor is built-in for all models

point 4

LCD keypad as standard

- Possible for palm top operation

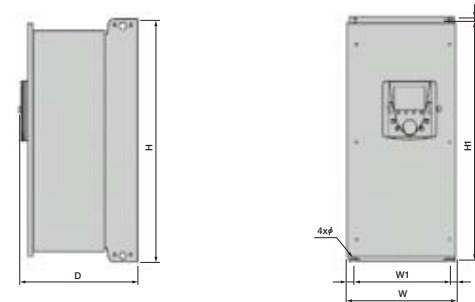
Standard specifications

Item	Specification																
Applicable motor (kW)	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	
Model	Type	VFPS1															
	Form	4007PLE	4015PLE	4022PLE	4037PLE	4055PLE	4075PLE	4110PLE	4150PLE	4185PLE	4220PLE	4300PLE	4370PLE	4450PLE	4550PLE	4750PLE	4900PLE
Rating	Capacity(KVA)Note 1)	1.8	3.1	3.9	6.9	9.1	12.0	17.0	23.0	28.0	33.0	45.0	54.0	65.0	78.0	104.0	124.0
	Output current(A) Note 2)	2.3	4.1	5.1	9.1	12	16	22.5	30.5	37	43.5	58.5	71.5	85	103	137	163
Power supply	Voltage/frequency	3-phase 380 to 480V, 50/60 Hz															
	Tolerance	Voltage +10%, -15% (±10% during continuous 100% load) Frequency ±5%															
Rated output voltage		3 phase 380 to 480V : 400V class (The maximum output voltage is same as the input source voltage)															
Output frequency range		0.01 to 500 Hz (Default setting 0.01 to 80.0 Hz)															
Overload current rating		110%~60 seconds (Anti-time limit characteristic)															
Dynamic breaking circuit		Built-in dynamic breaking circuit															
Dynamic breaking resistor		External option															
Main functions		Parameter setup quick mode, Local/remote operation, Automatic energy saving mode, programmable I/O terminal block, multi-PID control, Fire control enables forced operation, My function*															
Ambient temperature /Relative humidity		-10 to 50°C (current decreases when over 40°C)/5 to 95% (no condensation or steam allowed)															
Protective method		IP54/UL type 12															
Cooling method		Forced air cooling															
Built-in filter		EN55011 class A, EN61800-3 category C2 or C3 compliant (built-in EMI noise filter) :PLE type EN55011 class B, EN61800-3 category C1 compliant (built-in EMI noise filter) :PDE type *															
Reactor		Built-in DC reactor															

Note 1) Capacity is calculated at 440V

Note 2) Rated output current when the PWM carrier frequency(parameter CF) is 8kHz or less.

External dimensions



Input voltage Class	Applicable motor (kW)	Inverter model Note 1	Dimensions (mm)							Approximate Weight(kg) Note 1
			W	H	D	W1	H1	H2	ø	
3-phase 400 V	0.75	VFPS1-4007PLE(PDE)	240	490	272	200	476	6	6	12(14)
	1.5	VFPS1-4015PLE(PDE)								
	2.2	VFPS1-4022PLE(PDE)								
	3.7	VFPS1-4037PLE(PDE)	240	490	286	200	476	6	6	13(15)
	5.5	VFPS1-4055PLE(PDE)								
	7.5	VFPS1-4075PLE(PDE)								
	11	VFPS1-4110PLE(PDE)	260	525	286	220	511	6	6	16(19)
	15	VFPS1-4150PLE(PDE)								
	18.5	VFPS1-4185PLE(PDE)								
	22	VFPS1-4220PLE(PDE)	315	665	315	270	647	10	6	31(36)
	30	VFPS1-4300PLE(PDE)								
	37	VFPS1-4370PLE(PDE)								
	45	VFPS1-4450PLE(PDE)	285	720	315	245	700	10	7	34(39)
	55	VFPS1-4550PLE(PDE)								
	75	VFPS1-4750PLE(PDE)								
	90	VFPS1-4900PLE(PDE)	362	1000	364	300	975	10	9	69(80)

Note 1) The values in parentheses refer to PDE type.

VFPS1-****PLE:Built-in class A EMC filter, VFPS1-****PDE:Built-in class B EMC filter

Selection peripheral and wiring sizes devices

Voltage Class	Applicable motor (kW)	Inverter model	Input current[A]	Molded-case circuit breaker (MCCB) Note 1),2) Rated current [A]	Magnetic contactor (MC) Note 1),3),4),5) Operational current(A) AC1	Wire size Note 6),7)					
						Main circuit				Ground lead	
						Input terminal (R, S, T)		Output terminal (U, V, W)			
						AWG	mm2	AWG	mm2	AWG	mm2
400 V class	0.75	VFPS1-4007PLE(PDE)	1.	4	25	14	1.5	14	1.5	14	2.5
	1.5	VFPS1-4015PLE(PDE)	3.5	6.3	25	14	1.5	14	1.5	14	2.5
	2.2	VFPS1-4022PLE(PDE)	5	10	25	14	1.5	14	1.5	14	2.5
	3.7	VFPS1-4037PLE(PDE)	8.8	14	25	12	1.5	12	1.5	14	2.5
	5.5	VFPS1-4055PLE(PDE)	11.4	25	25	10	2.5	10	2.5	12	2.5
	7.5	VFPS1-4075PLE(PDE)	15.8	25	25	10	4	10	4	12	4
	11	VFPS1-4110PLE(PDE)	21.9	30	32	8	6	8	6	10	6
	15	VFPS1-4150PLE(PDE)	30.5	40	40	6	10	6	10	10	10
	18.5	VFPS1-4185PLE(PDE)	37.5	60	50	6	10	6	10	10	10
	22	VFPS1-4220PLE(PDE)	43.6	60	50	6	10	6	10	10	8
	30	VFPS1-4300PLE(PDE)	56.7	100	80	4	16	4	16	10	16
	37	VFPS1-4370PLE(PDE)	69.5	100	125	3	25	3	25	8	16
	45	VFPS1-4450PLE(PDE)	85.1	125	125	1	35	1	35	8	16
	55	VFPS1-4550PLE(PDE)	104.8	150	125	1/0	50	1/0	50	6	25
	75	VFPS1-4750PLE(PDE)	140.3	200	250	3/0	70	3/0	70	6	35
	90	VFPS1-4900PLE(PDE)	171.8	200	250	250MCM	120	250MCM	120	2	70

Note 1) Selections for use of the Toshiba 4-pole standard motor with power supply voltage of 400V-50Hz.

Note 2) Choose the MCCB according to the power supply capacity.

For comply with UL and CSA standard, use the fuse certified by UL and CSA.

Note 3) When the motor is driven by commercial power supply switching, for example, use an electromagnetic contactor that is matched to AC-3 class motor rated current.

Note 4) Attach surge killers to the magnetic contactor and exciting coil of the relay.

Note 5) In the case the magnetic contactor (MC) with 2a-type auxiliary contacts is used for the control circuit, raise the reliability of the contact by using 2a-type contacts in parallel connection.

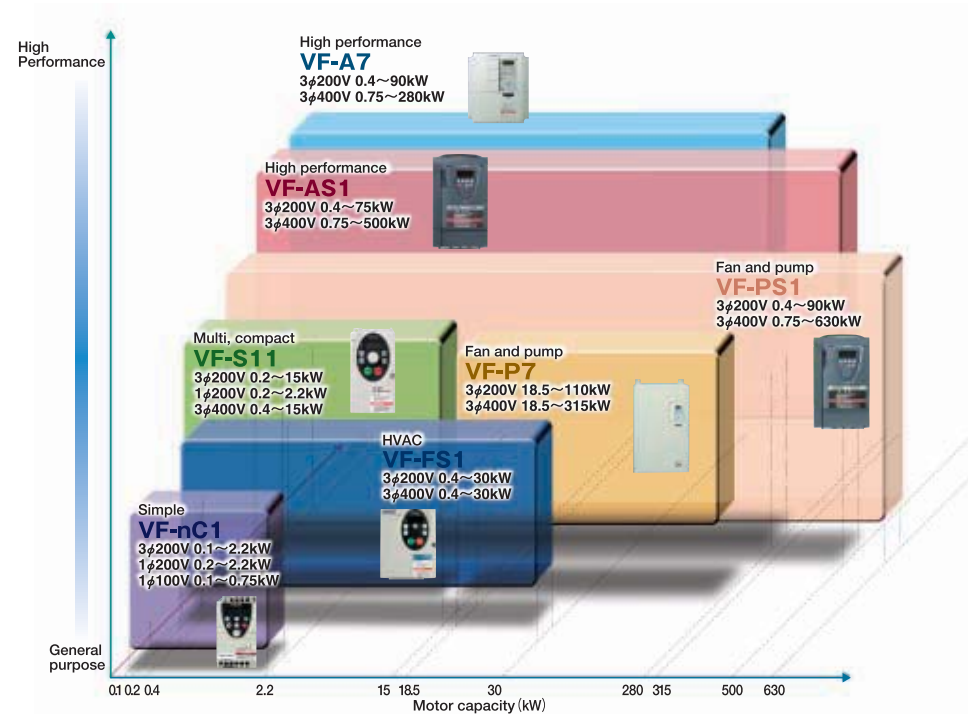
Note 6) The recommended cable size is that of the cable (e.g. 600V class, HIV cable) with continuous maximum permissible temperature of 75°C. Ambient temperature is 40°C or less and the wiring distance is 30m or less.

Note 7) For the control circuit, use shielded wires whose size (cross-section) is 0.75 mm² or more.

Note 8) The screw size of the control terminals is M3.

TOSHIBA Inverter lineup

The abundant variations of simple variable speed to vector control



Functions of lineup

Model	Voltage class	Applicable motor	Overload current rating	Automatic functions		Control specifications					Functions					
				Automatic acceleration / deceleration	Automatic torque boost	V/F constant	Automatic torque boost control	Energy-saving	Sensorless vector control	PG feedback vector control	Torque limit	Torque control	Positioning	Local/Remote	Fire control enables forced operation	LCD keypad option
VF-nC1	3φ200V	0.1 to 2.2kW	150%-1 minute	No	No	Yes	No	No	Yes	No	No	No	No	No	No	No
	1φ200V	0.2 to 2.2kW														
	1φ100V	0.1 to 0.75kW														
VF-S11	3φ200V	0.2 to 15kW	150%-1 minute	Yes	Yes	Yes	Yes	Yes	Yes	No	No	No	No	No	No	No
	1φ200V	0.2 to 2.2kW														
	3φ400V	0.4 to 15kW														
VF-AS1	3φ200V	0.4 to 75kW	150%-1 minute	Yes	Yes	Yes	Yes	No	Yes	Yes Note 1)	Yes	Yes	No	No	No	Yes Note 1)
	3φ400V	0.75 to 500kW														
VF-A7	3φ200V	0.4 to 90kW	150%-2 minute Note 2	Yes	Yes	Yes	Yes	Yes	Yes	Yes Note 1)	Yes	Yes	Yes Note 1)	No	No	No
	3φ400V	0.75 to 280kW														
VF-FS1	3φ200V	0.4 to 30kW	110%-1 minute	Yes	No	Yes	Yes	Yes	Yes	No	No	No	No	Yes	Yes	No
	3φ400V	0.4 to 30kW														
VF-PS1	3φ200V	0.4 to 90kW	120%-1 minute	Yes	No	Yes	Yes	Yes	Yes	Yes	No	No	No	Yes	Yes	Yes Note 1)
	3φ400V	0.75 to 630kW														
VF-P7	3φ200V	0.4 to 110kW	120%-1 minute	Yes	No	Yes	Yes	Yes	Yes	Yes	No	No	No	No	No	No
	3φ400V	0.75 to 315kW														

Note 1) Option

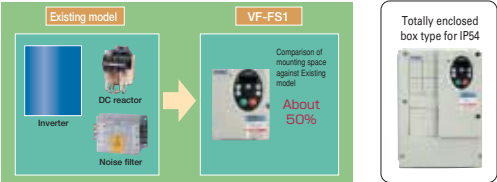
Note 2) For 200V-75kW or more and 400V-110kW or more, 150%-1 minute overload current rating

Inverter dedicated to fan and pump for HVAC

MEMO

VF-FS1

- Applications:
- AHUs
 - Ventilation fans
 - Chillers
 - Water pumps etc.



- POINT 1** Half installation space and less wiring
Reduce 50% of installation space, Built-in filter
- POINT 2** Reactor- less harmonic reduction
Toshiba unique technologies suppress harmonics Power factor improvement
- POINT 3** Long life and easy maintenance
15 years life designed main capacitors
- POINT 4** Special softwares for fan and pump application are built-in
Local/ Remote key, Fire control enables forced operation
- POINT 5** More energy saving and easier operation
The advanced energy- saving mode, Quick setting wizard

Optional filed buses for LONWORKS®, BACnet®, Metasys® N2 and APOGEE® FLN as built in option.

Standard specifications

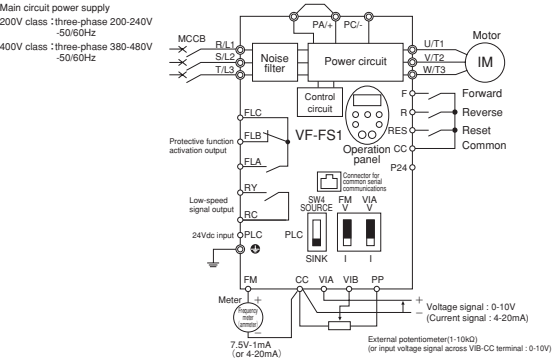
Item		Specification											
Applicable motor (kW)		0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30
Machine type	Input voltage class	VF-FS1											
	Model	VF-FS1											
Rating	3-phase 200V class	2004PM	2007PM	2015PM	2022PM	2037PM	2055PM	2075PM	2110PM	2150PM	2185PM	2220PM	2300PM
	3-phase 400V class	4004PL	4007PL	4015PL	4022PL	4037PL	4055PL	4075PL	4110PL	4150PL	4185PL	4220PL	4300PL
Capacity (kVA)	200V class/400V class	1.1	1.8/1.6	2.9/2.8	4.0/3.9	6.7/6.9	9.2/9.1	12.2	17.6/17.1	23.2	28.5/28.2	33.5/33.2	44.6
	Output current (A)	2.9	4.6	7.5	10.6	17.5	24.2	32	46.2	61	74.8 (67.3)	98 (79.2)	117.0 (105.3)
Power supply	3-phase 200V class	2.9	4.6	7.5	10.6	17.5	24.2	32	46.2	61	74.8 (67.3)	98 (79.2)	117.0 (105.3)
	3-phase 400V class	1.4	2.2	3.7	5.1	9.1	12	16	22.5	30.5	37 (33.3)	43.5 (39.2)	58.5 (52.7)
Voltage/frequency	200V class	200V to 240V - 50/60Hz											
	400V class	3-phase 380 to 480V - 50/60Hz											
Tolerance	200V class	Voltage +10%, -15% (±10% when the inverter is used continuously (load of 100%))											
	400V class	Adjustable within a range of the corrected supply voltage 50 to 660V (Inadjustable to any voltage higher than the input voltage).											
Output voltage adjustment	200V class	0.5 to 200.0Hz (default setting 0.5 to 80.0Hz)											
	400V class	Adjustable within a range of the corrected supply voltage 50 to 660V (Inadjustable to any voltage higher than the input voltage).											
Output frequency range	200V class	0.5 to 200.0Hz (default setting 0.5 to 80.0Hz)											
	400V class	Adjustable within a range of the corrected supply voltage 50 to 660V (Inadjustable to any voltage higher than the input voltage).											
Voltage/frequency characteristics	200V class	V/f constant, variable torque, automatic torque boost, vector control, automatic energy conservation, PM motor control, auto-tuning function											
	400V class	V/f constant, variable torque, automatic torque boost, vector control, automatic energy conservation, PM motor control, auto-tuning function											
Overload current rating	200V class	60 seconds at 110%, 2 seconds at 180% (Anti-time limit characteristic)											
	400V class	60 seconds at 110%, 2 seconds at 180% (Anti-time limit characteristic)											
Main functions	200V class	Wizard, Local/Remote change-over, Bumpless operation, Forced fire-speed control, PTC thermal protection, Programmable I/O terminal block, Auto-restart											
	400V class	Wizard, Local/Remote change-over, Bumpless operation, Forced fire-speed control, PTC thermal protection, Programmable I/O terminal block, Auto-restart											
Ambient temperature/Relative humidity	200V class	-10 to 60°C (Current decrease when over 40°C) /20 to 93% free from condensation and vapor											
	400V class	-10 to 60°C (Current decrease when over 40°C) /20 to 93% free from condensation and vapor											
Protective method	200V class	0.4 to 18.5kW - IP20 enclosed type(JEM1030), 22kW and over : IP00 type(JEM1030)											
	400V class	0.4 to 18.5kW - IP20 enclosed type(JEM1030), 22kW and over : IP00 type(JEM1030)											
Cooling method	200V class	Forced air cooling											
	400V class	Forced air cooling											
Built-in filter	200V class	3-phase 200V class: basic noise filter, 400V class EM noise filter (IEC/EN51800-3, 1st Environment C2 or IEC/EN51800-3, 2nd Environment C3)											
	400V class	3-phase 200V class: basic noise filter, 400V class EM noise filter (IEC/EN51800-3, 1st Environment C2 or IEC/EN51800-3, 2nd Environment C3)											

The rated output current in the parenthesis is at 12kHz of PWM carrier frequency(F300)setting.

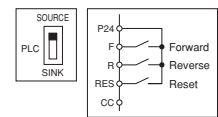
Exterior dimensions and weight

Input voltage class	Applicable motor(kW)	Inverter model	Dimensions(mm)			Approximate weight(kg)
			Width	Height	Depth	
3-phase 200V (IP20/IP00)	0.4	VFFS1-2004PM	107	130	150	1.2
	0.75	VFFS1-2007PM	107	130	150	1.2
	1.5	VFFS1-2015PM	107	130	150	1.2
	2.2	VFFS1-2022PM	107	130	150	1.2
	3.7	VFFS1-2037PM	142	170	150	2.1
	5.5	VFFS1-2055PM	180	220	170	4.3
	7.5	VFFS1-2075PM	180	220	170	4.3
	11	VFFS1-2110PM	245	310	190	8.6
	15	VFFS1-2150PM	245	310	190	8.6
	18.5	VFFS1-2185PM	245	310	190	8.9
	22	VFFS1-2220PM	240	420	214	16.4
	30	VFFS1-2300PM	320	630	290	38
3-phase 400V (IP20/IP00)	0.4	VFFS1-4004PL	107	130	150	1.4
	0.75	VFFS1-4007PL	107	130	150	1.4
	1.5	VFFS1-4015PL	107	130	150	1.4
	2.2	VFFS1-4022PL	107	130	150	1.4
	3.7	VFFS1-4037PL	142	170	150	2.4
	5.5	VFFS1-4055PL	142	170	150	2.4
	7.5	VFFS1-4075PL	180	220	170	4.7
	11	VFFS1-4110PL	180	220	170	4.7
	15	VFFS1-4150PL	245	310	190	9
	18.5	VFFS1-4185PL	245	310	190	9
	22	VFFS1-4220PL	240	420	214	15.4
	30	VFFS1-4300PL	240	420	214	15.4

Standard connection diagram : Sink logic(common : cc)



Standard connection diagram : Source logic(common : P24)



To users of our inverters : Our inverters are designed to control the speeds of three-phase induction motors for general industry.

Precautions

- * Read the instruction manual before installing or operating the inverter unit and store it in a safe place for reference.
- * When using our inverters for equipment such as nuclear power control, aviation and space flight control, traffic, and safety, and there is a risk that any failure or malfunction of the inverter could directly endanger human life or cause injury, please contact our headquarters, branch, or office printed on the front and back covers of this catalogue. Special precautions must be taken and such applications must be studied carefully.
- * When using our inverters for critical equipment, even though the inverters are manufactured under strict quality control always fit your equipment with safety devices to prevent serious accident or loss should the inverter fail (such as issuing an inverter failure signal).
- * Do not use our inverters for any load other than three-phase induction motors.
- * None of Toshiba, its subsidiaries, affiliates or agents, shall be liable for any physical damages, including, without limitation, malfunction, anomaly, breakdown or any other problem that may occur to any apparatus in which the Toshiba inverter is incorporated or to any equipment that is used in combination with the Toshiba inverter. Nor shall Toshiba, its subsidiaries, affiliates or agents be liable for any compensatory damages resulting from such utilization, including compensation for special, indirect, incidental, consequential, punitive or exemplary damages, or for loss of profit, income or data, even if the user has been advised or apprised of the likelihood of the occurrence of such loss or damages.

For further information, please contact your nearest Toshiba Representative or International Operations-Producer Goods.
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